Algorithm Analysis

- Performance Relations
 - Time and Space
- Classification of algorithms
- Comparison between classes
- Statistical cases best, average, worst
- Example analysis
 - Bubble sort
 - Binary search

Time & Space Performance estimates

Time performance

- the relationship between the size of the data collection and time to process
- Example: sort an array of n elements –

Space performance

- the relationship between the memory required to solve a problem and the problem size
- Example: sort a list of integers with 2 stacks the extra stack space represents an overhead.



T and S are described in terms of the size of the problem (number of elements)

• **Time = T(n)**

- time to solve a problem with **input size n**
- Space = S(n)
 - space to solve a problem with input size n

Performance

- The relationship between the input size and time/space
- If n is the size of the input
 - Ex: $T(n) = n^2 + 3n$
 - Ex: S(n) = log(n)

Performance

- To compare the performance of algorithms we use T(n) and S(n)
- These are written in the form: O(n)
- O is pronounced (Big-Oh) O is the Order of growth
- O determines a performance class
- Comparing algorithms on an abstract level uses
 Big-O as an <u>INDICATOR</u> of the performance

O(n) – how is T(n) used?

- Rule of thumb: for T(n) = 3n⁴ + n² the class is O(n⁴)
 - For large values of n, n^4 is more significant than n^2
- Mathematically for T(n) = 3n⁴ + n² there exists a class O(cn⁴) where cn⁴ >= T(n) for some c
 - For $T(n) = n^2 + 2n + 1$, for what c is $cn^2 \ge T(n)$?
 - c = 4, n = 1, therefore the class is $O(4n^2)$
- Constants in O-notation disappear, $O(5n^2 + 3) \equiv O(n^2)$
 - The reason: the constant does not depend on n
 - Since O denotes a class T(n) belongs to some class O,
 T(n) = n² + 2n + 1 ∈ O(n²)

O(n) (continued)

How many different classes are there??

Infinitely many... BUT only a few are of interest

 $O(1), O(log (n)), O(n), O(n log(n)), O(n^2), O(n^3), \\ \dots, O(x^n), \dots, O(n!), \dots, O(n^n) \dots$

The performance is given in decreasing order

Diagram



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From the diagram

- Certain problems do not fall into these classes
 - Ex: **7n**² is **better** than **100n** for problem with **size < 14**
 - This is despite the fact that $O(n^2)$ is worse than O(n)
- Assume that **n** is quite large:- therefore **big-O** is significant
- Implementing an algorithm which is O(n!) is not a good idea!

Sorting has different Big-Oh solutions

- 1. To sort a sequence with 2 elements is **O(1)**
 - o requires max 2 operations:
 - o compare the elements and swap.
- To sort an already sorted sequence in reverse order requires O(n²)
- To sort a random sequence takes O(n log(n)) (quicksort)
- These are called **best**, worst and average cases
- In general, the <u>average case</u> is of most interest as long as the <u>worst case</u> does not occur often

Analysis of bubble sort

bubble(A) for i = 1 upto A.size - 1 for j = A.size downto i+1 **if** A[j-1] > A[j] then swap(A[j-1], A[j]) end for end for end bubble

- n = array size
- Outer loop executes n times
- Inner loop executes x times
 x är n i

n-1 n-iifsats & swap i=1 j=n

Bubble sort (continued)

- The inner loop executes **n-1** times
- i is decided by the outer loop
- The if and swap execute (n 1) + (n 2) + (n 3) + ... + (n n) times
- If you remember arithmetic series then (n 1) * n / 2 times
- This gives $(n^2 n) / 2 \rightarrow O(n^2)$



$$T(n) = \frac{n^2 - n}{2} \in O(n^2)$$

Example analysis (continued)

Binary search analysis

- n = array size
- The first time we are looking for 1 element in n
- The next time 1 element in n / 2
- The next time n / 2 / 2 element
- ...
- Finally there is one element left in the search space
- How many times did we divide the search space?

```
binsearch(A, v, l, r)
  let m = (l + r) / 2
  if A[m] == v then return m
  else if l==r then return NOTFOUND
  else if v < A[m]
  then return binsearch(A,v,l,m-1)
  else return binsearch(A,v,m+1,r)
end binsearch</pre>
```

r

8

9

4

3

m

5

6

7

2

Example analysis (continued)

- In other words how many times do we have to partition the search space before we have 1 element (worst case)?
- Suppose that the number of partitions is k and array size n
- Then:

$$\frac{n}{2^k} = 1 \Longrightarrow k = \log_2 n \Longrightarrow k = c \cdot \log n$$

- since k is the number of operations required to solve a problem with input size n, therefore T(n) = k
- if $T(n) = c \log(n)$, then $T(n) \in O(\log(n))$

Rules of Thumb for Analysis

- Ex 1: Nested loops. Big-O is
 - O(n^{number of loops}) if the loop depends on N
- Ex 2: "divide and conquer" algorithm.
 - Such algorithms are logarithmic.
 - A decision is made which divides the problem space, the choice eliminates a part of the problem.
 - The rule is **O(log(n))**

Tips

- **Do not analyse algorithms** waste of time! (wot ⁽²⁾)
- **Do not write your own algorithms** to solve known problems
- Use already proven and certified algorithms
- If you have to choose between well-known algorithms
 - Choose on the basis of problem size (n)
 - If (n) is of arbitrary size
 - choose the algorithm with the best Big-O classification
 - If the algorithms have the same Big-O classification
 - Consider T(n) and/or S(n) performance
 - Consider the best / worst / average case