

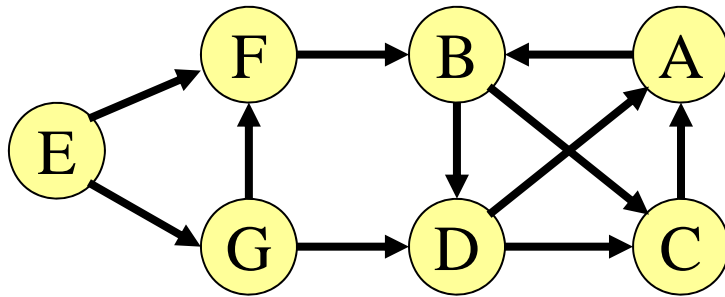
[Digraphs: Depth First Search]

Given $G = (V, E)$ and all v in V are marked unvisited, a depth-first search (dfs) (generalisation of a pre-order traversal of tree) is one way of navigating through the graph

- **select one v in V and mark as visited**
- **select each unvisited vertex w adjacent to v - dfs(w) (recursive!)**
- **if all vertices marked \Rightarrow search complete**
- **otherwise select an unmarked node and apply dfs**

implementation: adjacency list

DFS: Example

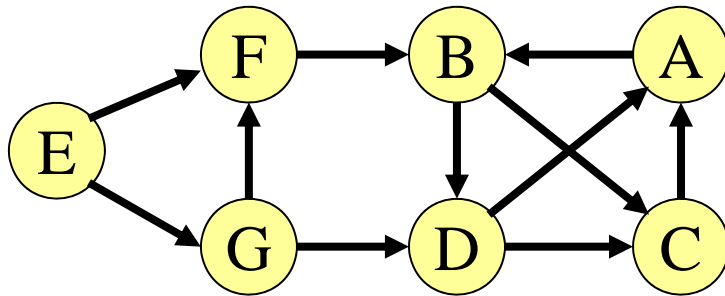


Start: A

A, B, C, D, E, F, G

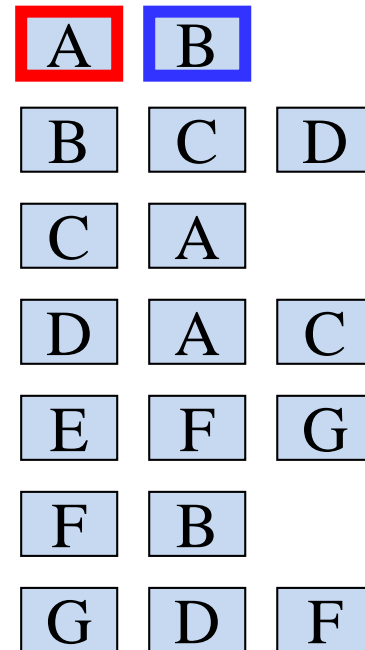
A	B	
B	C	D
C	A	
D	A	C
E	F	G
F	B	
G	D	F

DFS: Example

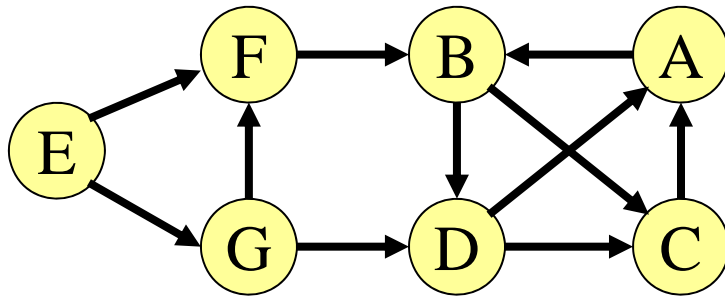


Start: A

A → B

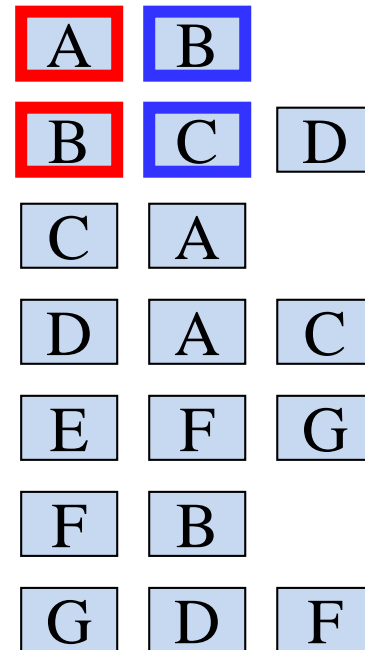


DFS: Example

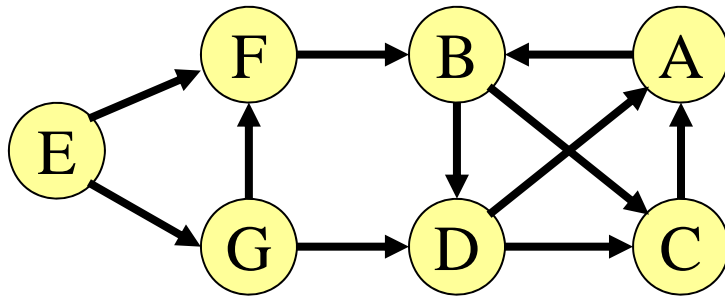


Start: A

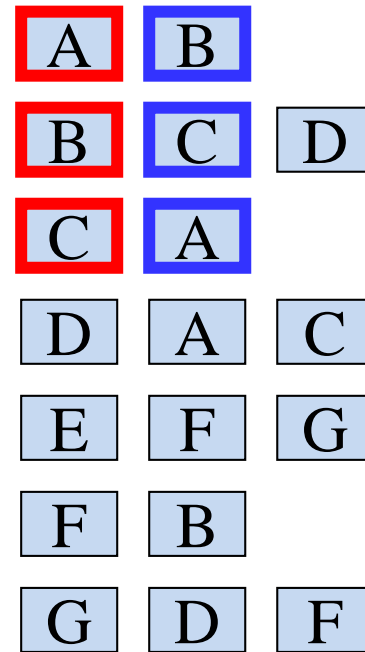
A → B → C



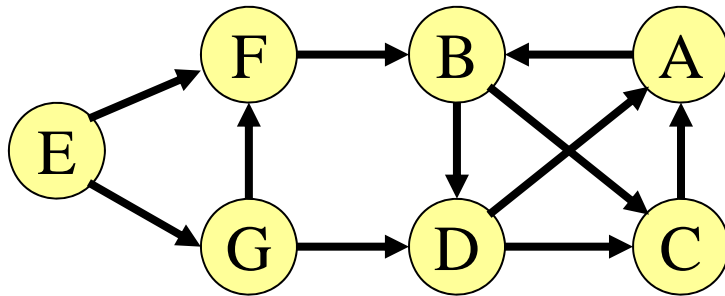
DFS: Example



Start: A
A → B → C

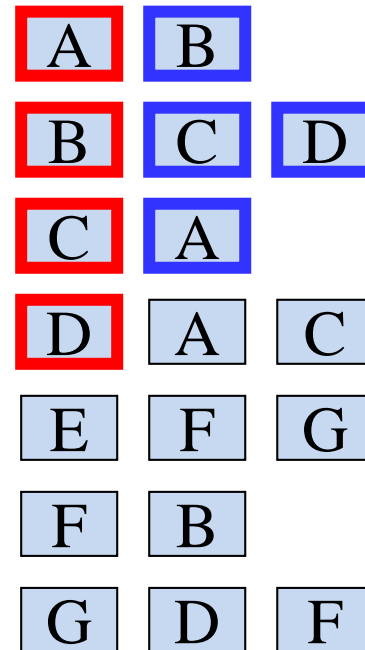


DFS: Example

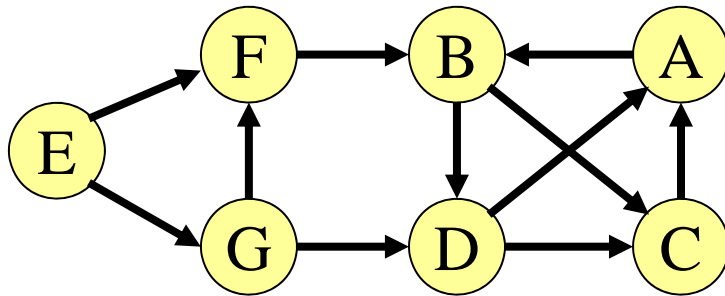


Start: A

$A \rightarrow B \rightarrow C, B \rightarrow D$

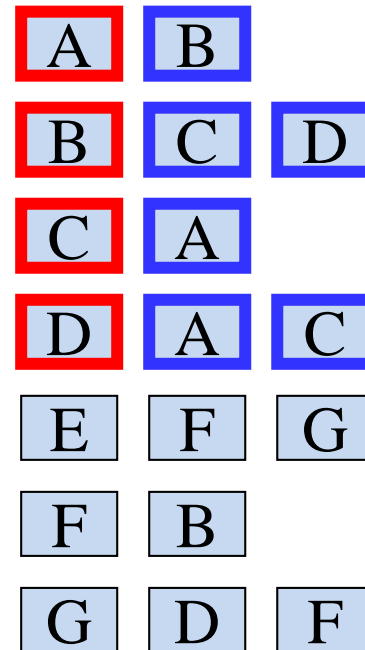


DFS: Example

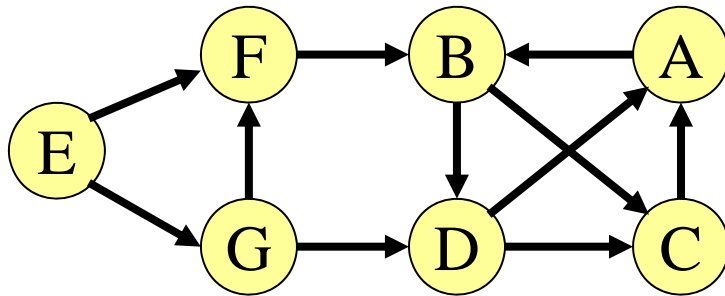


Start: A

$A \rightarrow B \rightarrow C, B \rightarrow D$



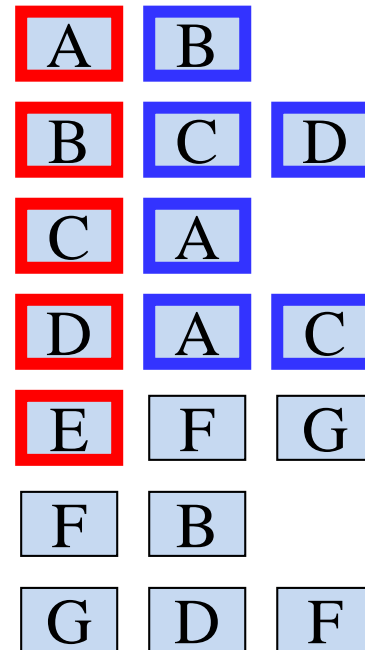
DFS: Example



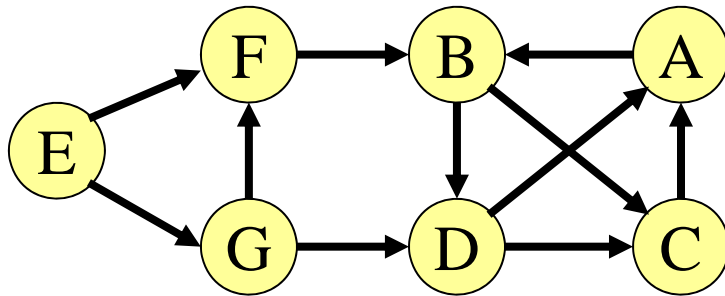
Start: A

A → B → C, B → D

Start E



DFS: Example

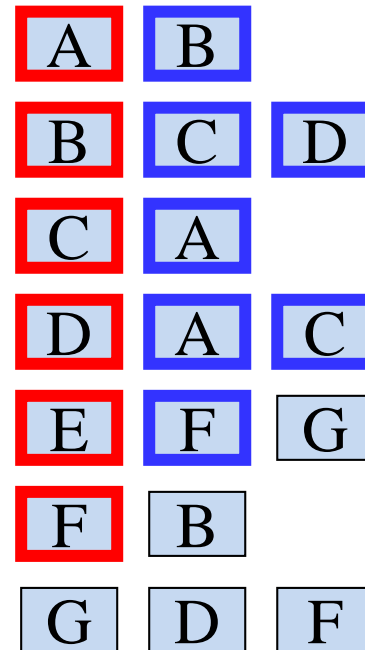


Start: A

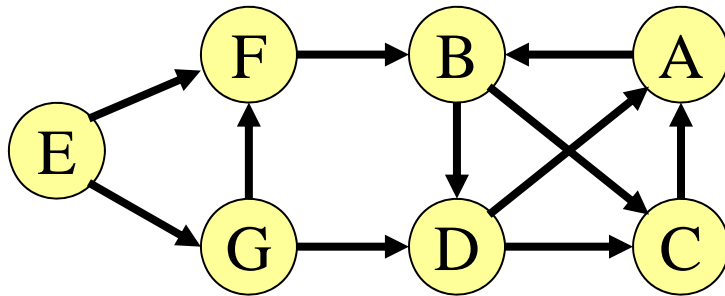
A → B → C, B → D

Start: E

E → F



DFS: Example

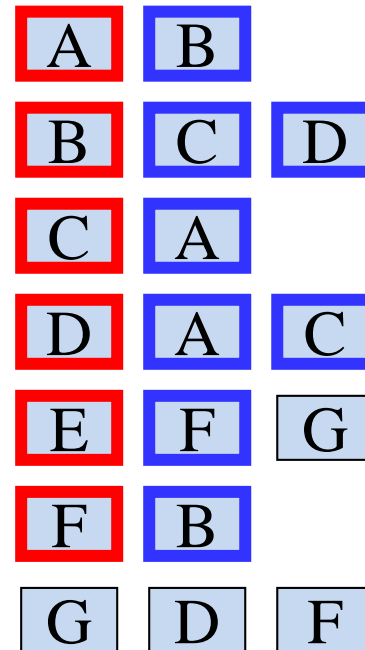


Start: A

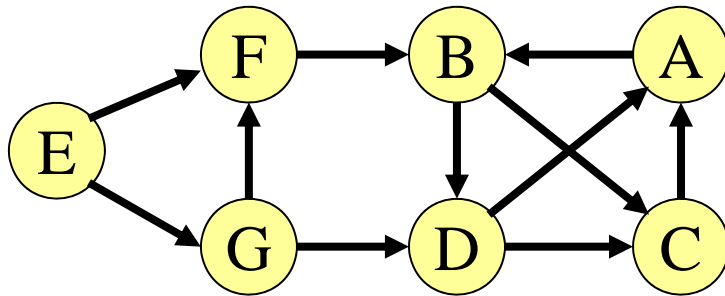
A → B → C, B → D

Start: E

E → F



DFS: Example

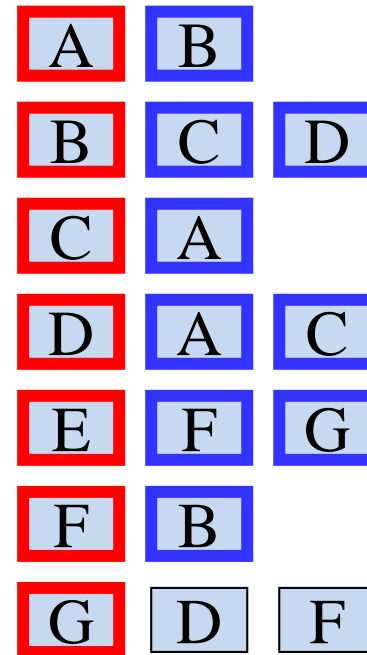


Start: A

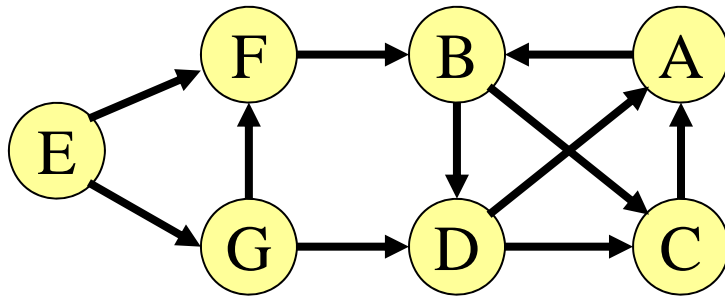
A → B → C, B → D

Start: E

E → F, E → G



DFS: Example

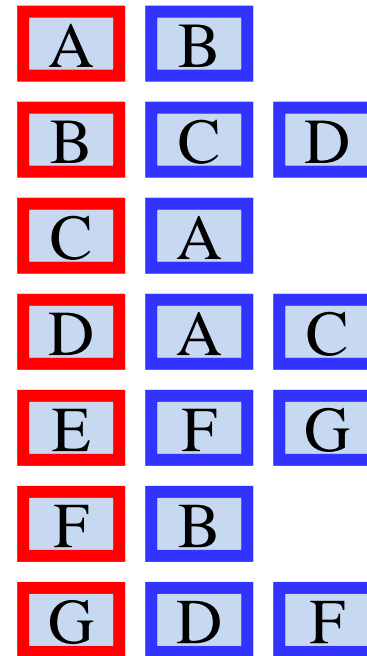


Start: A

A → B → C, B → D

Start: E

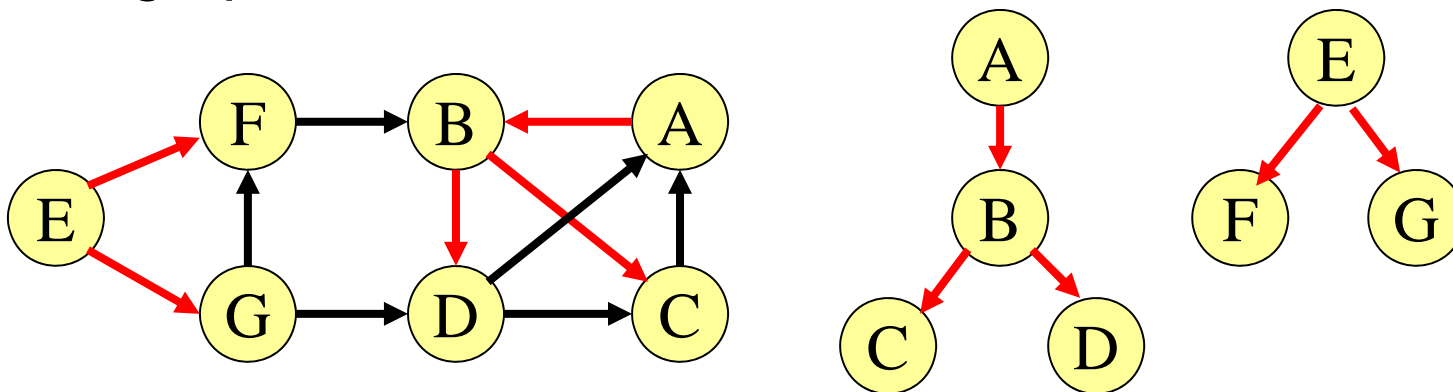
E → F, E → G



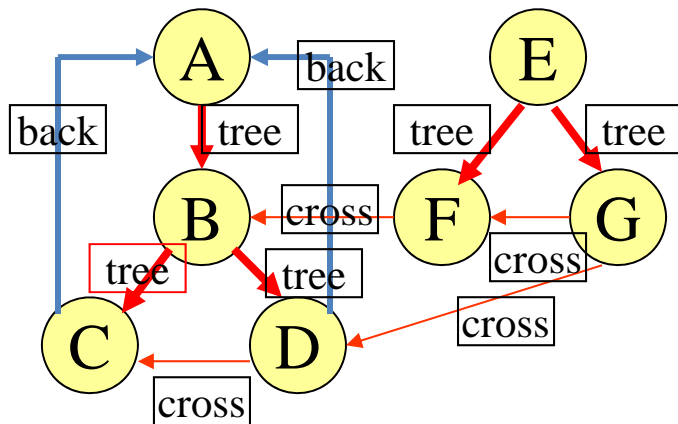
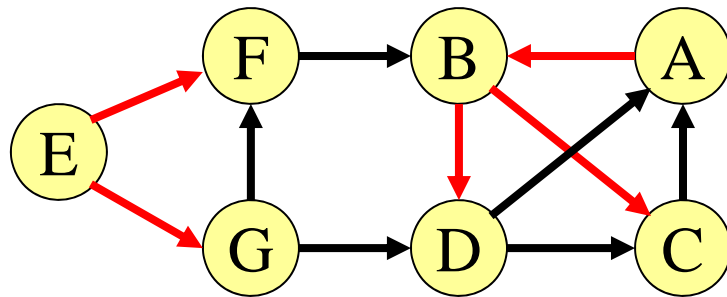
Depth First Spanning Forest

in a dfs of a directed graph, certain edges, when visited, lead to unvisited vertices

such edges are called TREE EDGES and form a DEPTH FIRST SPANNING FOREST for the given digraph

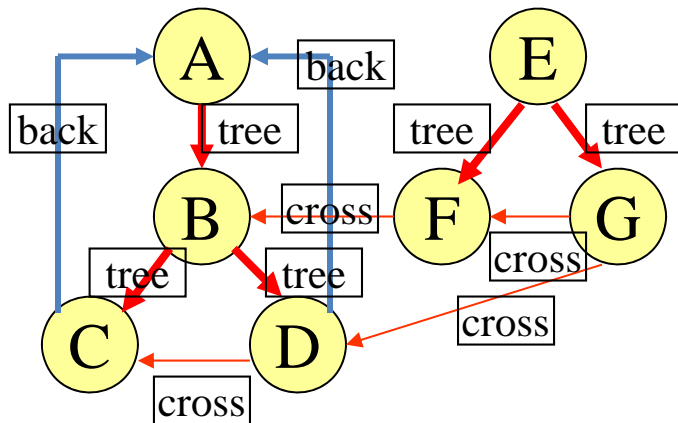
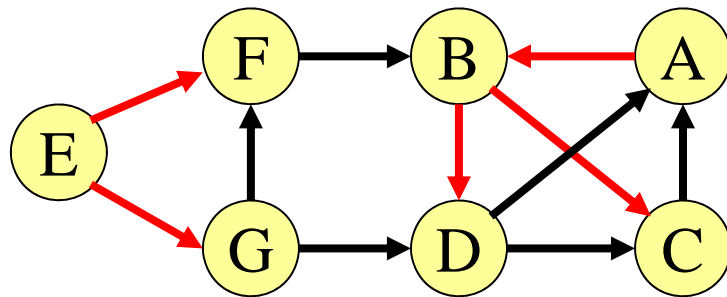


Depth First Spanning Forest



- Other edges are
 - back edge
 - vertex to an ancestor
 - forward edge
 - non-tree edge from a vertex to a proper descendant (in the tree)
 - cross edge
 - edge from V_1 to V_2 - neither an ancestor nor descendant

Depth First Spanning Forest

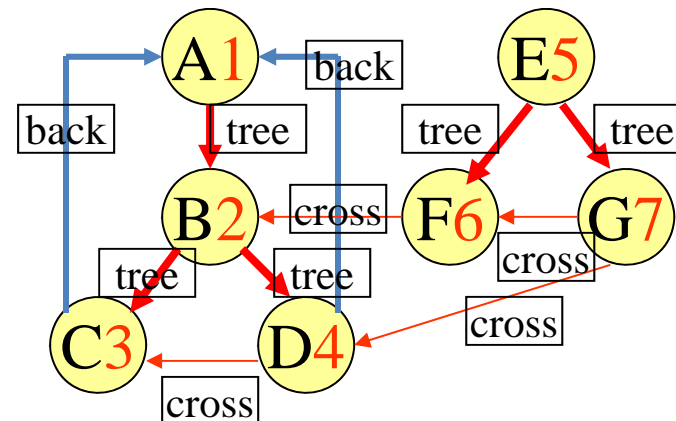


- Nota Bene (NB)
 - all cross edges go from right to left assuming that
 - children added to tree in order visited (l to r)
 - new trees added to forest in left to right order
- vertices can be numbered (dfn) in depth first order

A	B	C	D	E	F	G
1	2	3	4	5	6	7

Depth First Spanning Forest

- **All descendants** of v have $\text{dfn}(v) \geq \text{dfn}(w)$
- **forward edges**
low dfn to high dfn
- **back edges**
high dfn to low dfn
- **cross edges**
high dfn to low dfn
- **back edge \Rightarrow cycle**
- w is a descendant of v iff
 - $\text{dfn}(v) \leq \text{dfn}(w) \leq \text{dfn}(v) + \text{number of descendants of } v$

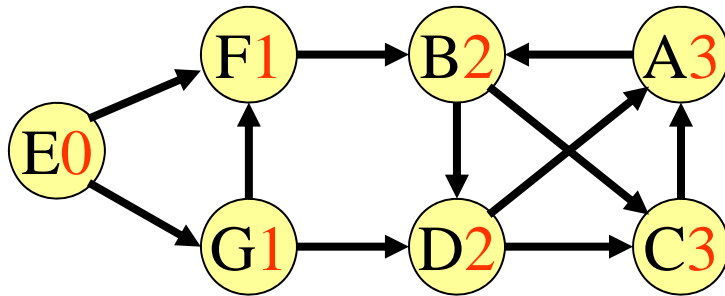


Digraphs: Breadth First Search

Given $G = (V, E)$ and all v in V are marked unvisited, a breadth-first search (bfs) is another way of navigating through the graph

```
select one  $v$  in  $V$  and mark as visited; enqueue  $v$  in  $Q$   
while not is_empty( $Q$ ) {  
     $x = \text{front}(Q); \text{dequeue}(Q);$   
    for each  $y$  in adjacent ( $x$ ) if unvisited ( $y$ ) {  
        mark( $y$ ); enqueue  $y$  in  $Q$ ; process ( $x,y$ )  
        // (e.g. add to tree);  
    }  
}
```

[BFS: Example]

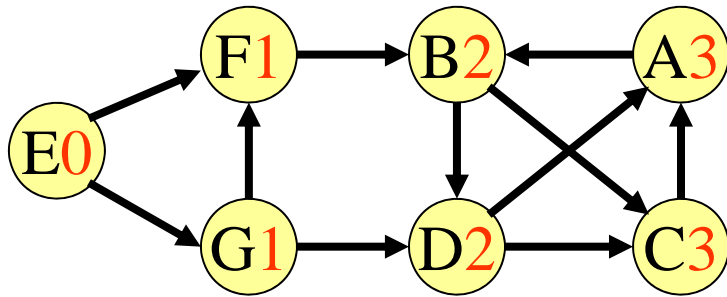


Start: E

Output: E, F, G, B, D, C, A

A	B	
B	C	D
C	A	
D	A	C
E	F	G
F	B	
G	D	F

[BFS: Example]

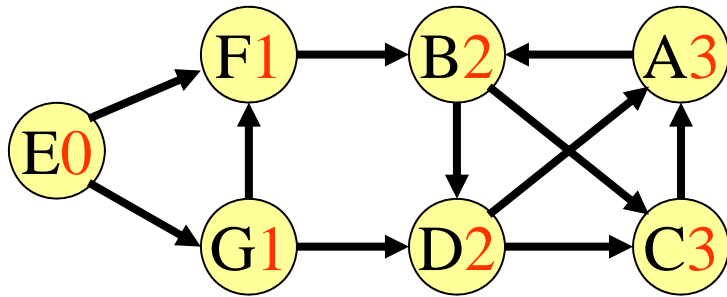


Start: E

Q: E

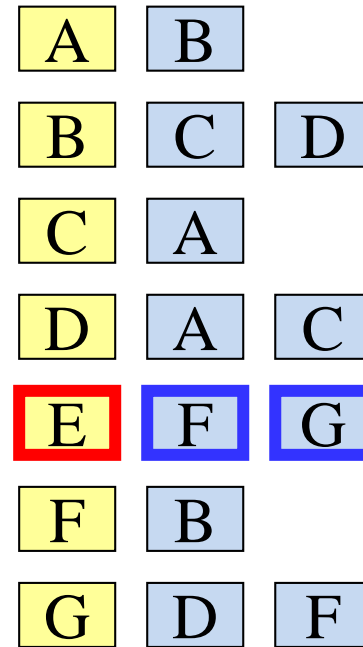
A	B	
B	C	D
C	A	
D	A	C
E	F	G
F	B	
G	D	F

[BFS: Example]

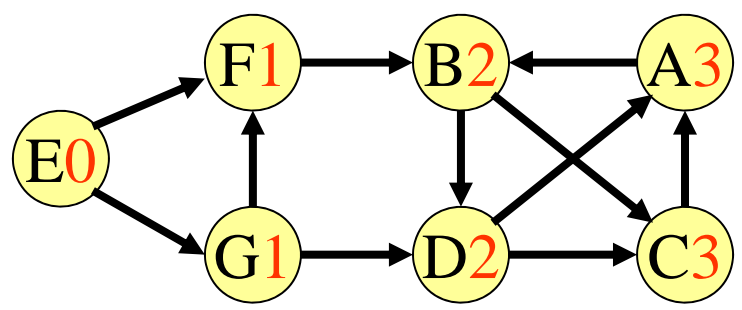


Start: E

Q: F, G



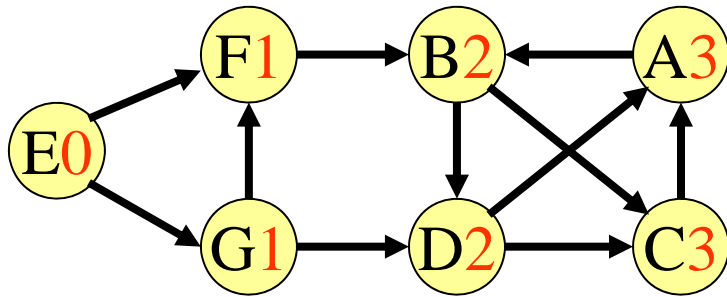
[BFS: Example]



Start: E
Q: G

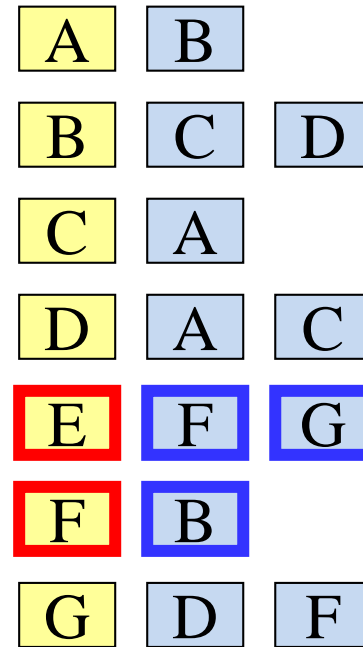
A	B	
B	C	D
C	A	
D	A	C
E	F	G
F	B	
G	D	F

[BFS: Example]

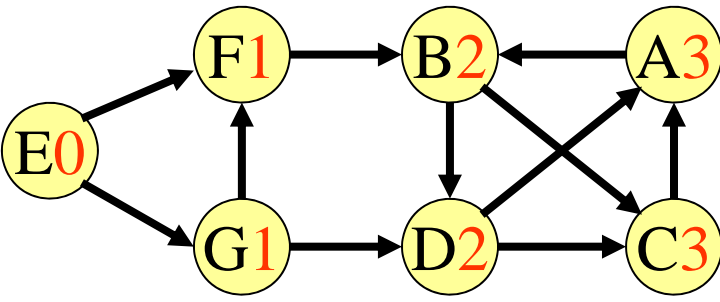


Start: E, F

Q: G, B



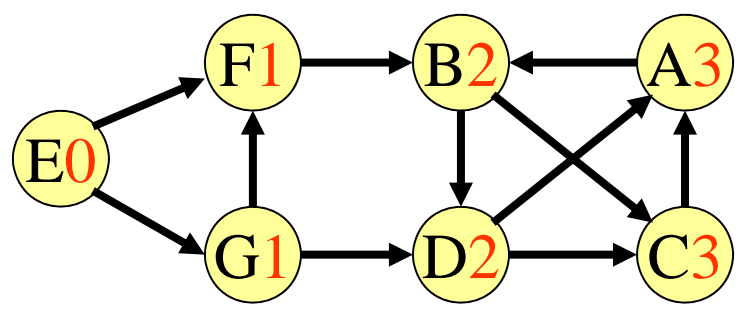
[BFS: Example]



Start: E, F, G
 Q: B, D

A	B	
B	C	D
C	A	
D	A	C
E	F	G
F	B	
G	D	F

[BFS: Example]

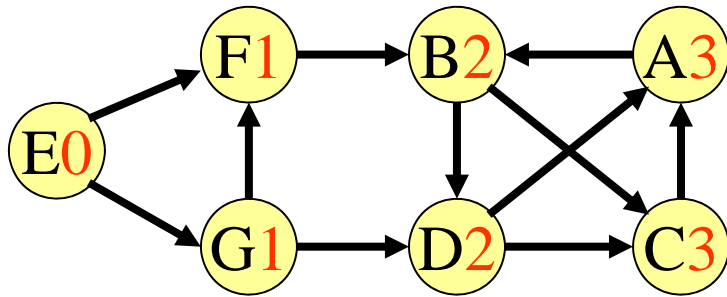


Start: E, F, G, B

Q: D

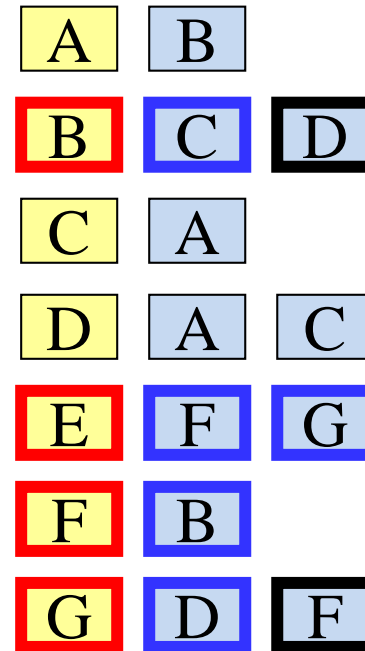
A	B	
B	C	D
C	A	
D	A	C
E	F	G
F	B	
G	D	F

[BFS: Example]

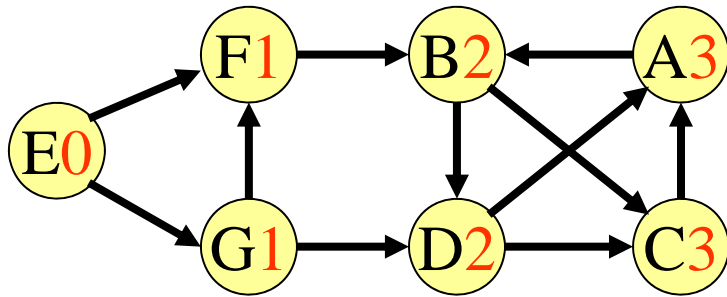


Start: E, F, G, B

Q: D, C

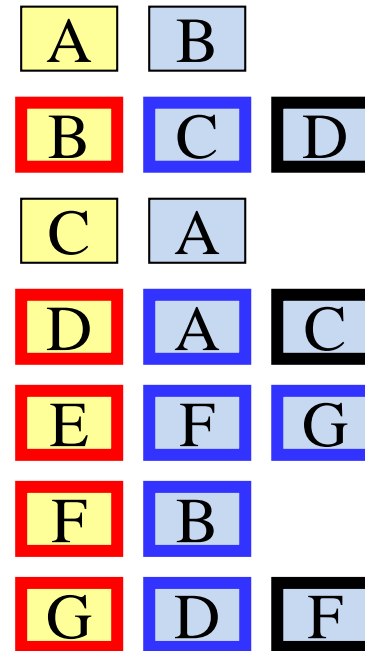


[BFS: Example]

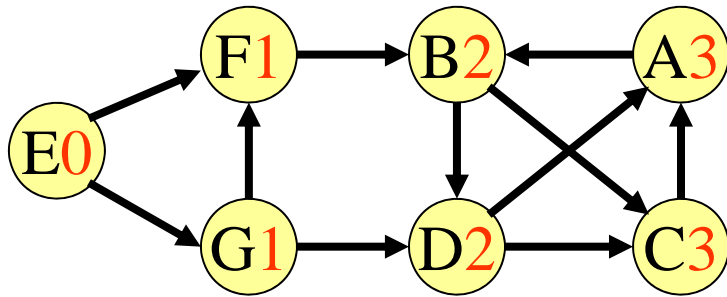


Start: E, F, G, B, D

Q: C, A

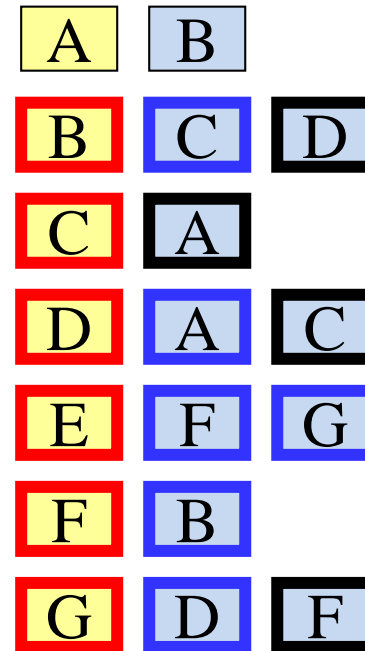


[BFS: Example]

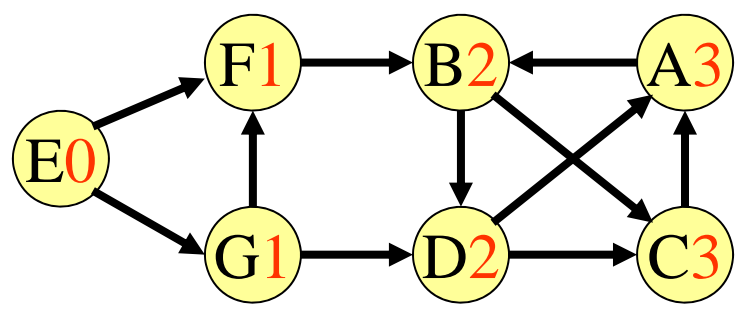


Start: E, F, G, B, D, C

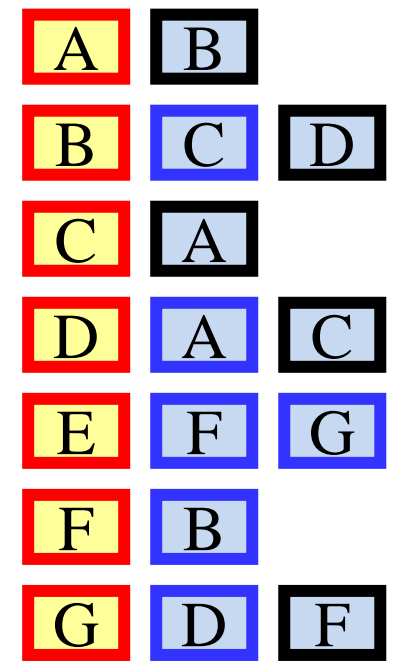
Q: A



[BFS: Example]



Start: E, F, G, B, D, C, A
 Q: empty

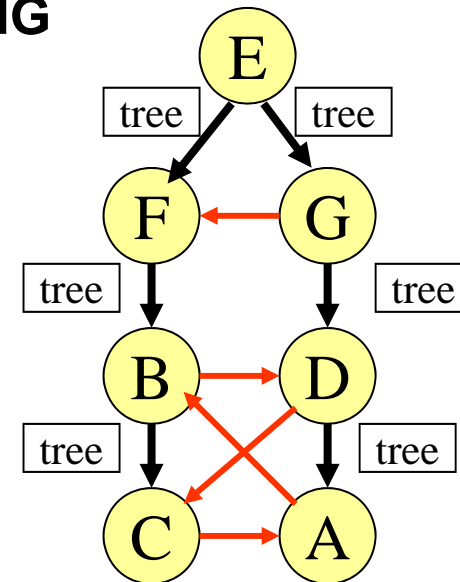
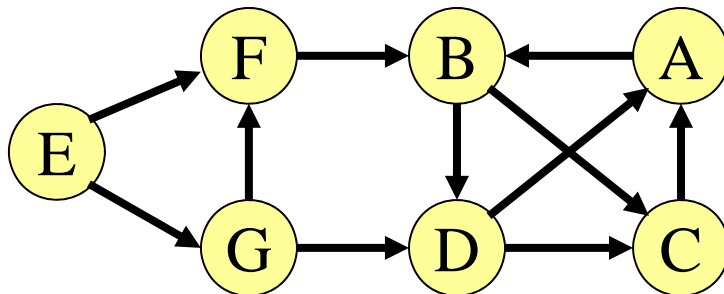


Breadth First Spanning Forest

in a bfs of a directed graph, certain edges, when visited, lead to unvisited vertices- such edges are called **TREE EDGES**

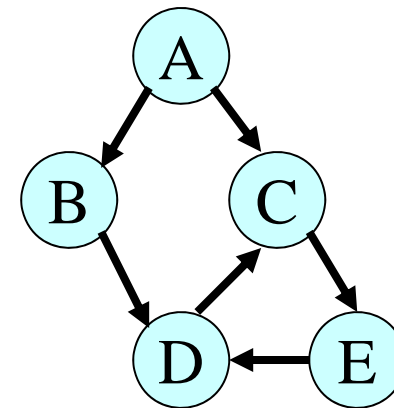
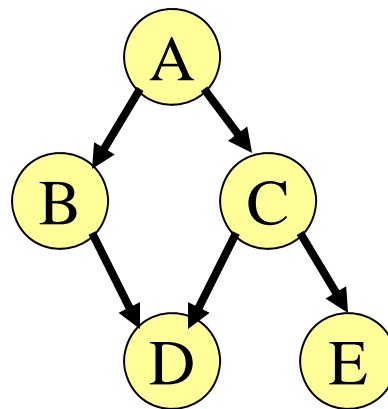
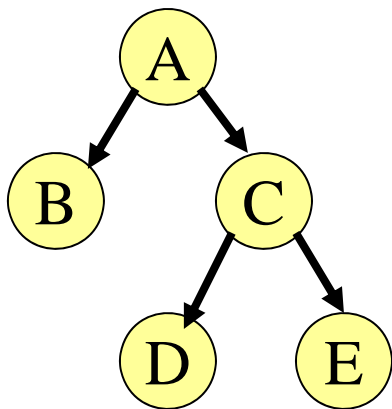
and form a **BREADTH FIRST SPANNING FOREST** for the given digraph

NB only tree & non-tree (cross) edges



Directed Acyclic Graphs (DAGs)

- DAG - digraph with no cycles
- compare: tree, DAG, digraph with cycle

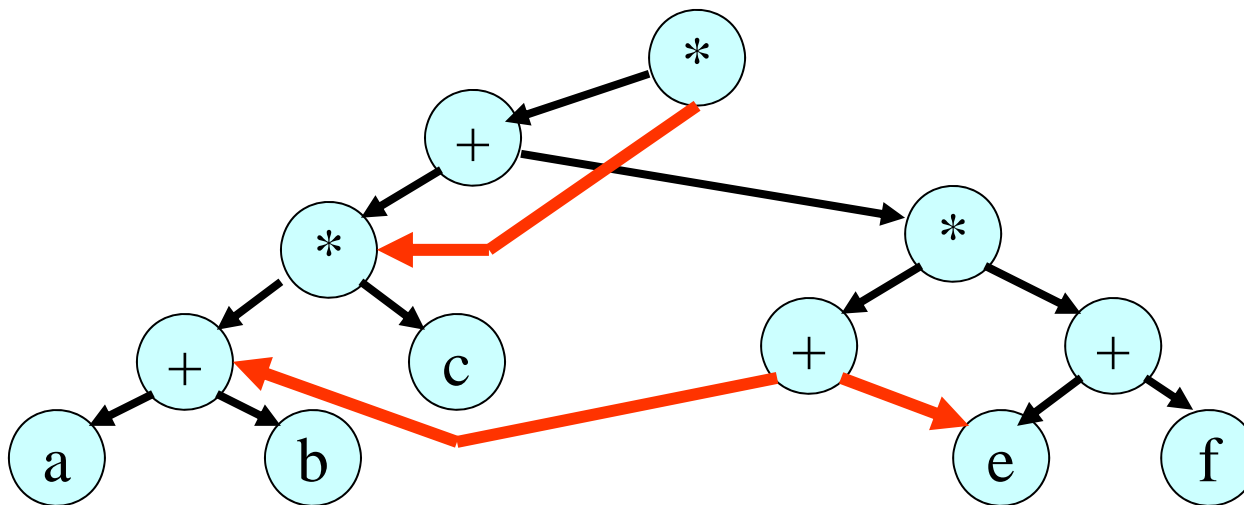


- Tree in-degree = 1 out-degree = 2 (binary)
- DAG in-degree ≥ 1 out-degree ≥ 1

[DAG: use]

- Syntactic structure of arithmetic expressions with common sub-expressions

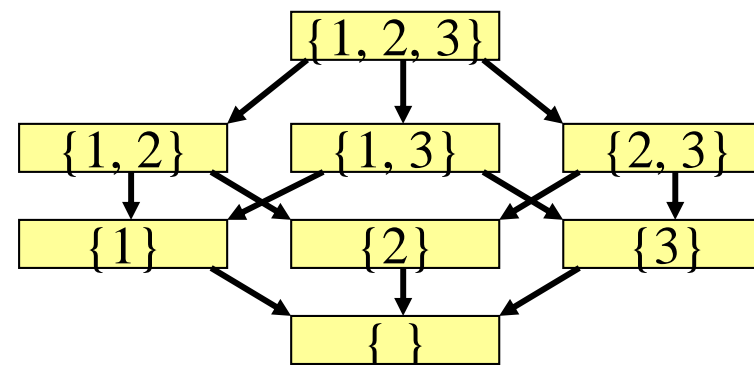
e.g. $((a+b)*c + ((a+b)+e)*(e+f)) * ((a+b)*c)$



DAG: use

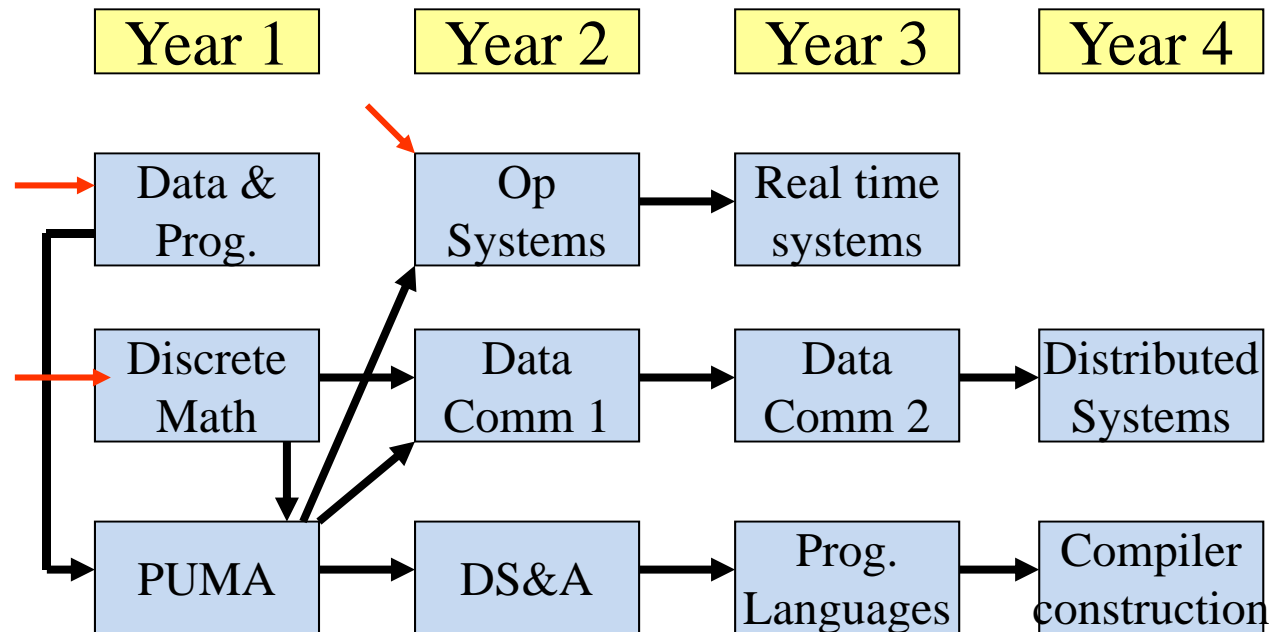
- To represent **partial orders**
- A partial order R on a set S is a binary relation such that
 - for all a in S $a R a$ is false (**irreflexive**)
 - for all a, b, c in S if $a R b$ and $b R c$ then $a R c$ (**transitive**)
- examples: “less than” ($<$) and proper containment on sets

- $S = \{1, 2, 3\}$
- $P(S)$ - power set of S
(set of all subsets)



DAG: use

- To model course prerequisites or dependent tasks

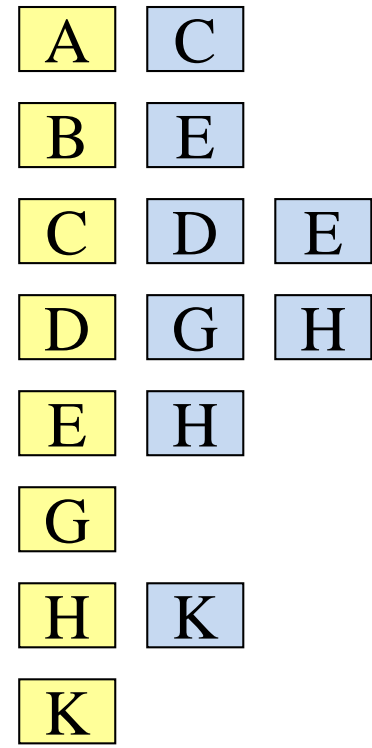
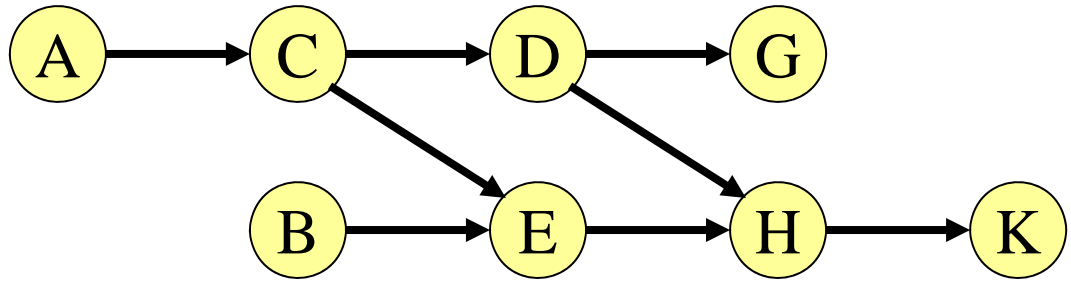


[Topological sort]

- Given a DAG of prerequisites for courses, a topological sort can be used to determine **an order** in which to take the courses
- (TS: DAG => sequence) (modified dfs)
- prints **reverse** topological order of a DAG from v

```
tsort(v) {  
    mark v visited  
    for each w adjacent to v if w unvisited tsort(w)  
    display(v)  
}
```

Topological sort: example



start: A

tsort(A) =>
reverse =>

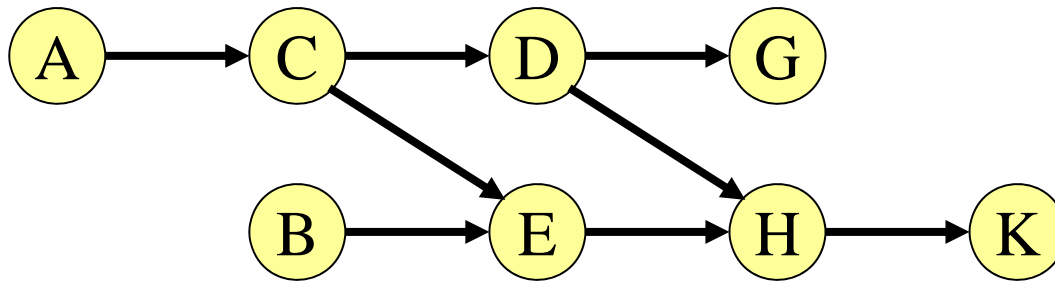
G K H D E C A B
 B A C E D H K G

Topological Sort example

```

tsort(v) {
  A → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

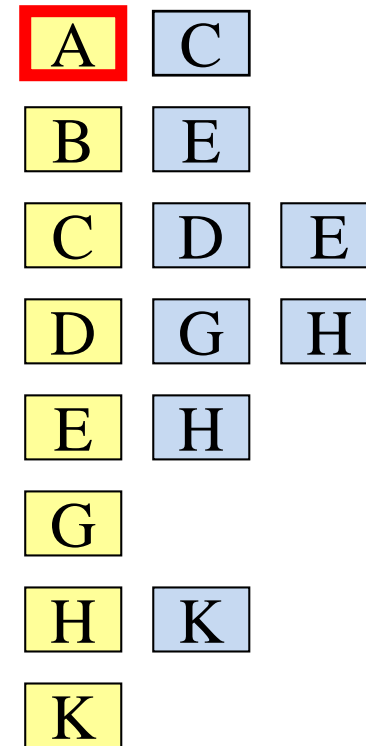
```



path: A

output:

reverse:

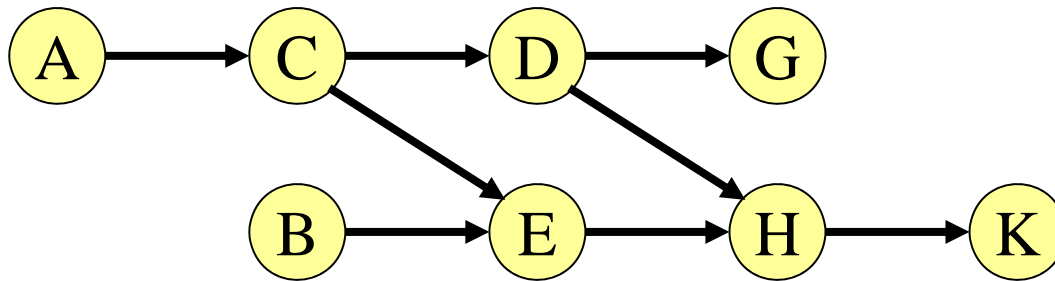


Topological Sort example

```

tsort(v) {
    mark v visited
    A→ for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

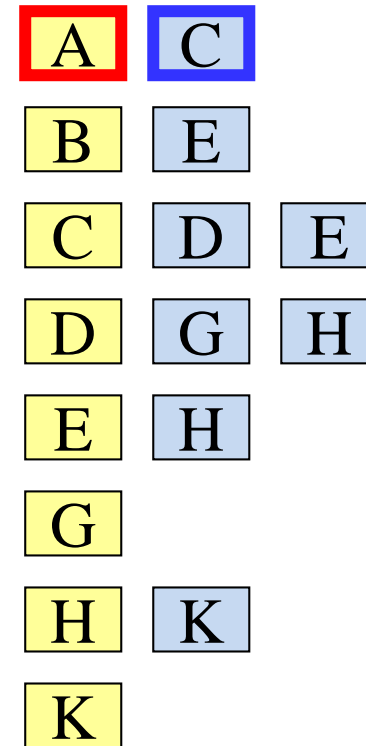
```



path: **A → C**

output:

reverse:

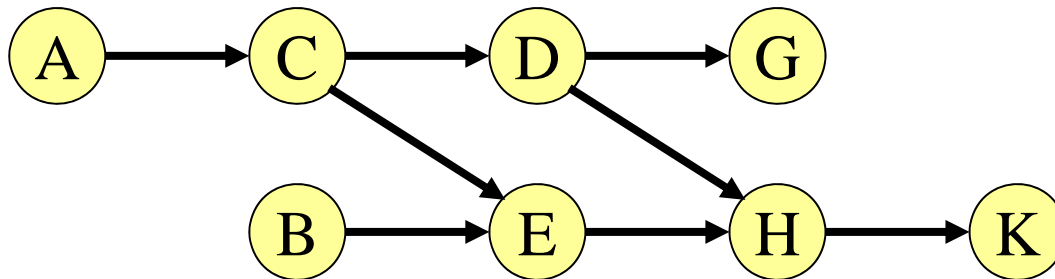


Topological Sort example

```

tsort(v) {
  C → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

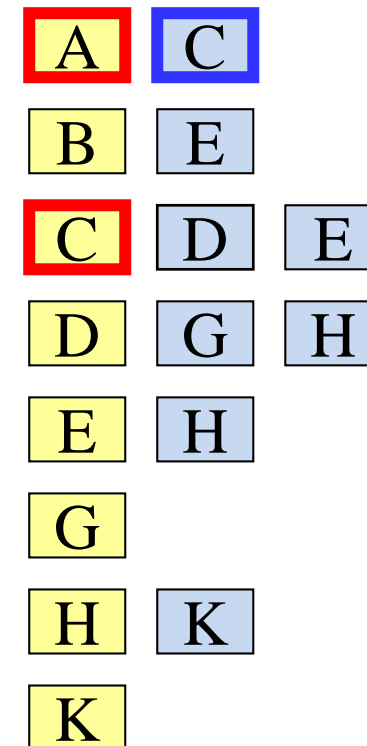
```



path: **A → C**

output:

reverse:

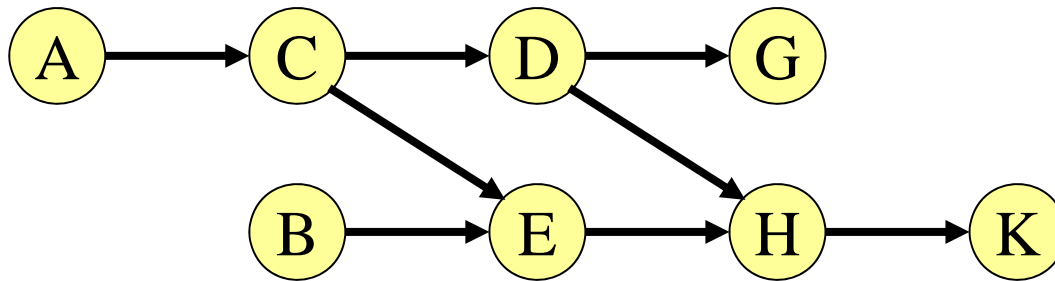


Topological Sort example

```

tsort(v) {
    mark v visited
    C → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

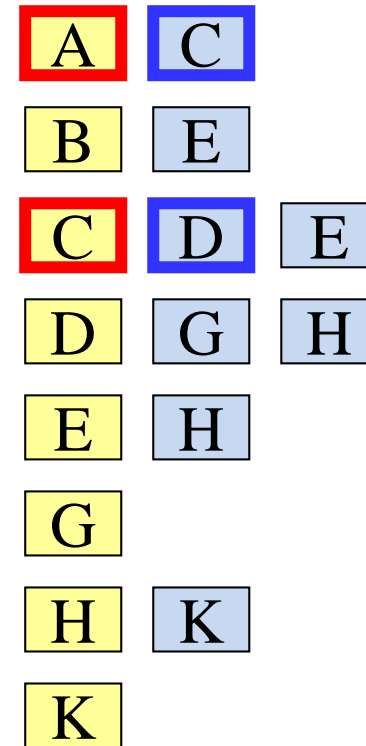
```



path: **A → C → D**

output:

reverse:

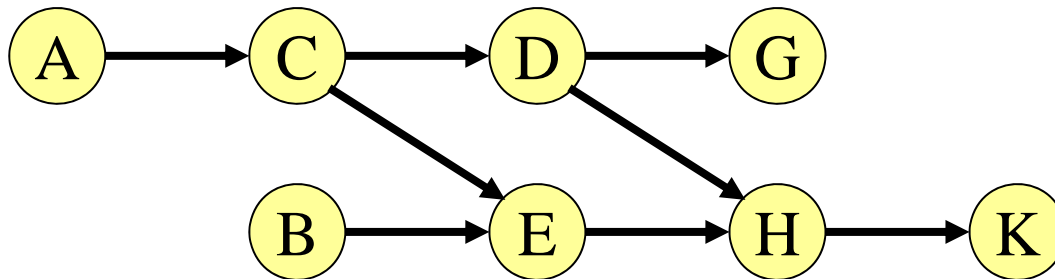


Topological Sort example

```

tsort(v) {
  D → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

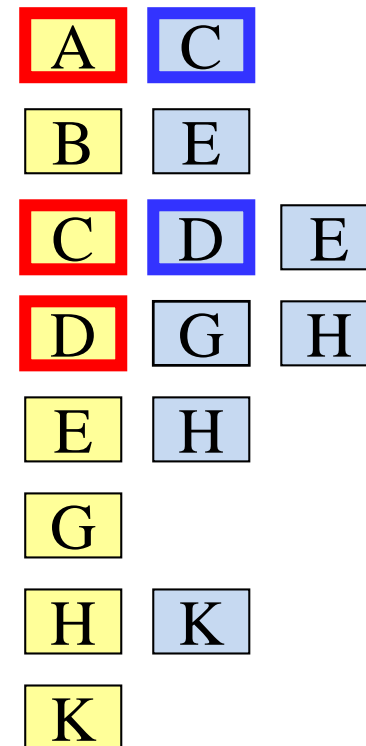
```



path: **A → C → D**

output:

reverse:

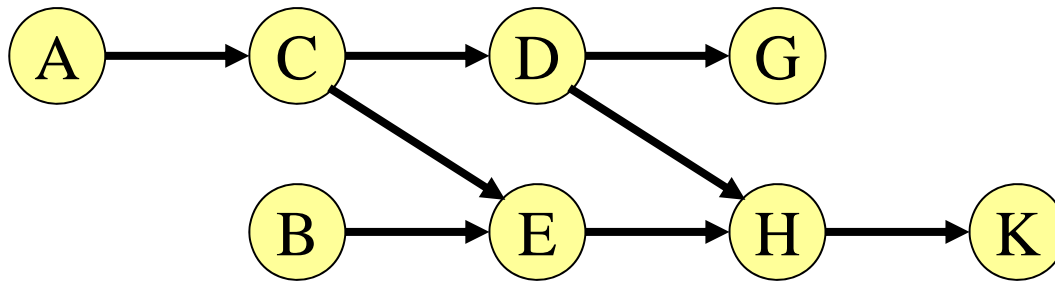


Topological Sort example

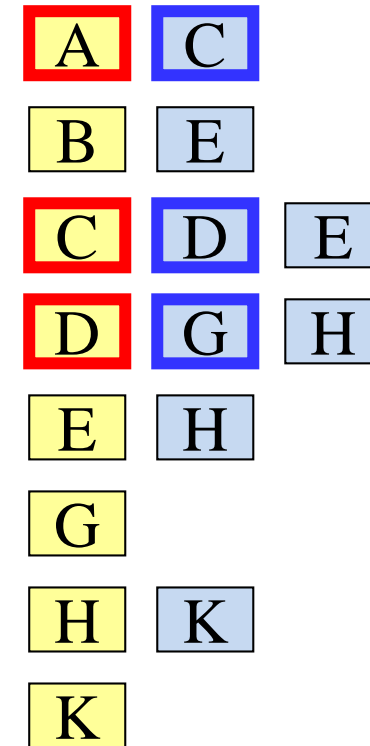
```

tsort(v) {
    mark v visited
    D → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

```



path: **A → C → D → G**
output:
reverse:

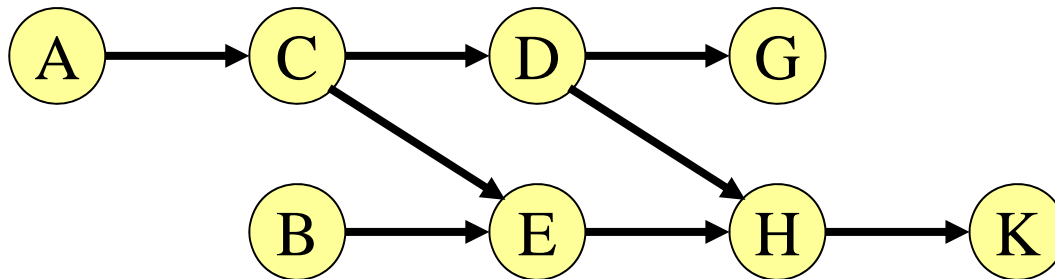


Topological Sort example

```

tsort(v) {
  G → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

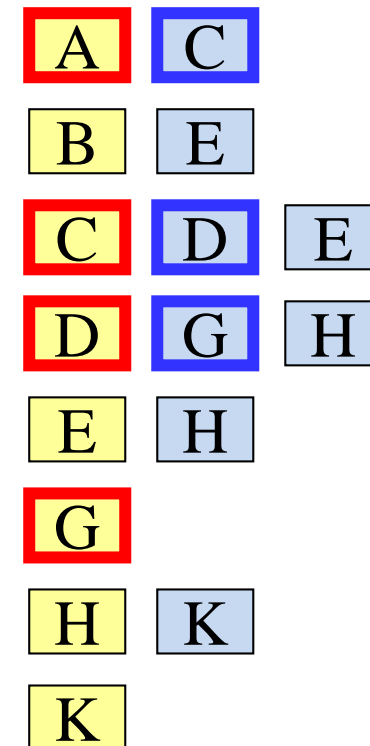
```



path: **A → C → D → G**

output:

reverse:

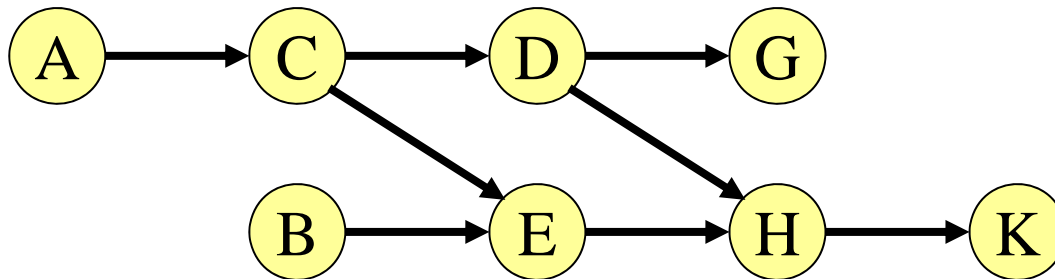


Topological Sort example

```

tsort(v) {
    mark v visited
    G → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

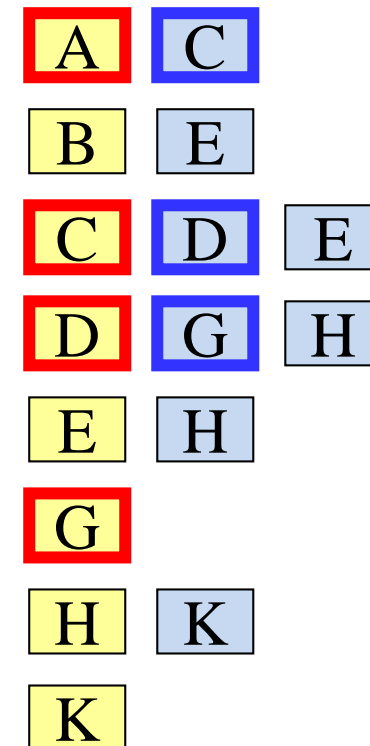
```



path: **A → C → D → G**

output:

reverse:

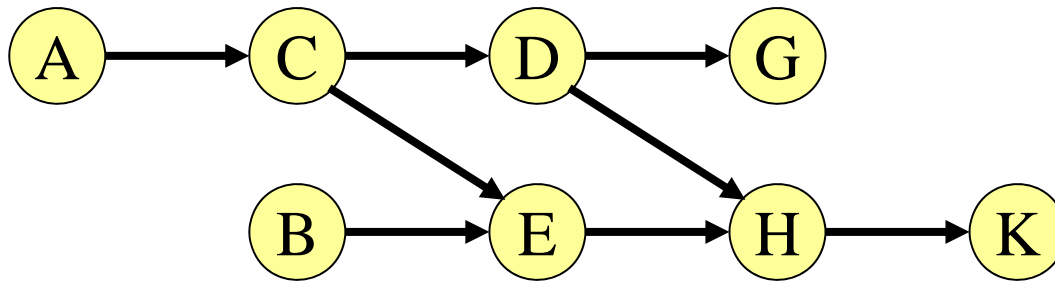


Topological Sort example

```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    G → display(v)
}

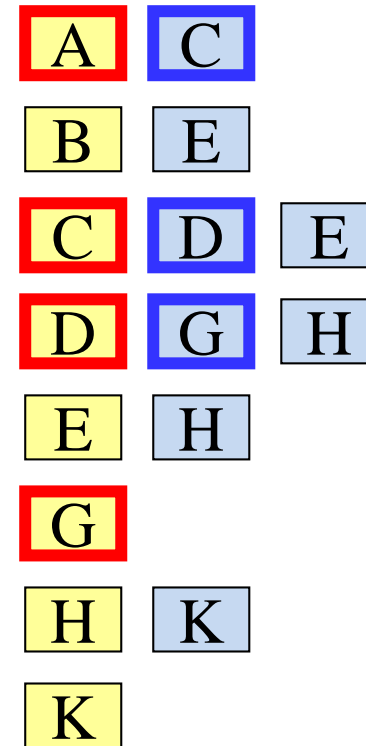
```



path: **A → C → D → G**

output: **G**

reverse:

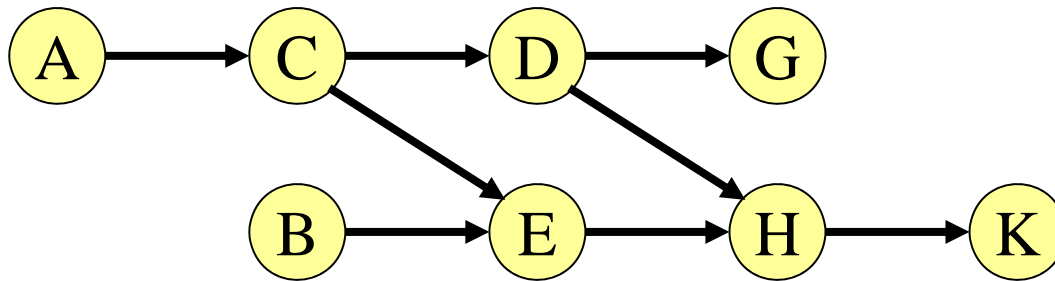


Topological Sort example

```

tsort(v) {
    mark v visited
    D → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

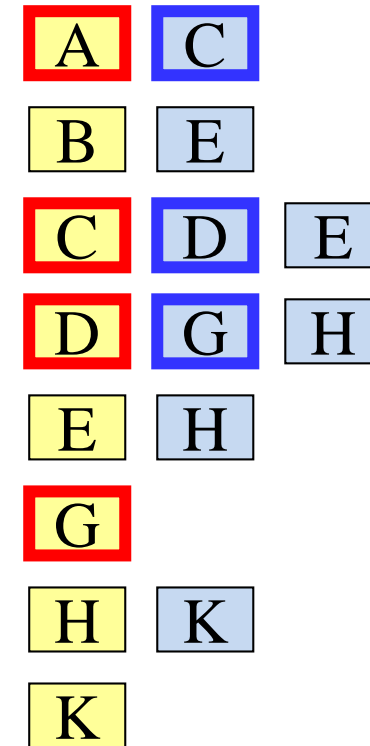
```



path: **A → C → D**

output: **G**

reverse:

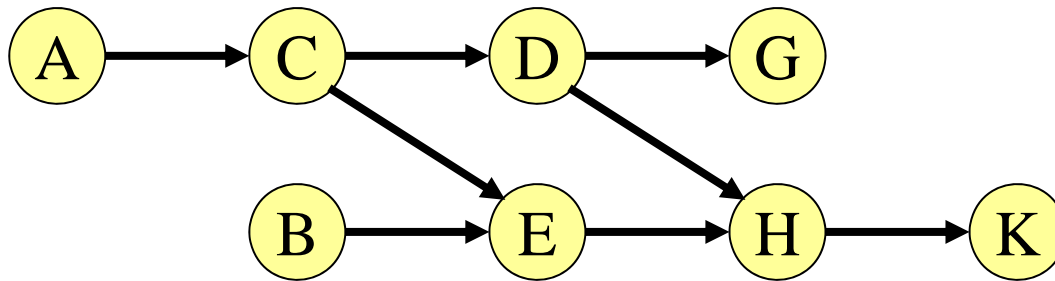


Topological Sort example

```

tsort(v) {
    mark v visited
    D → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

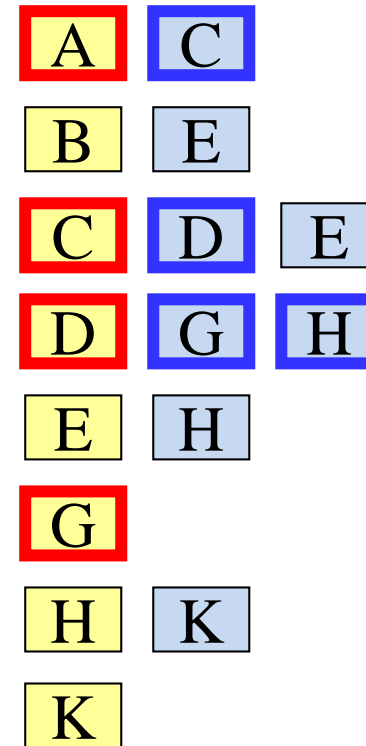
```



path: **A → C → D → H**

output: **G**

reverse:

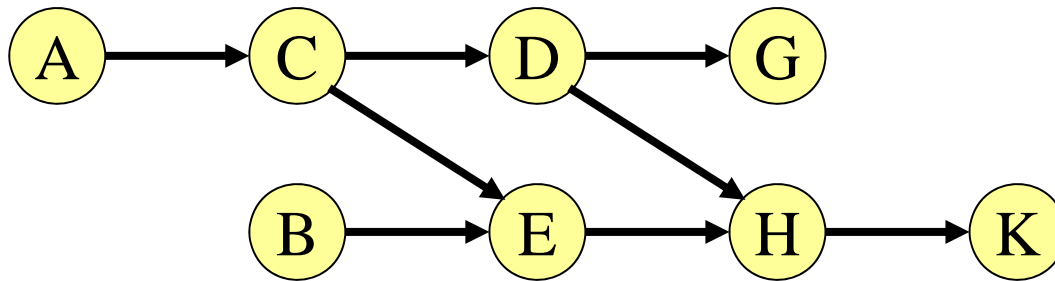


Topological Sort example

```

tsort(v) {
  H → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

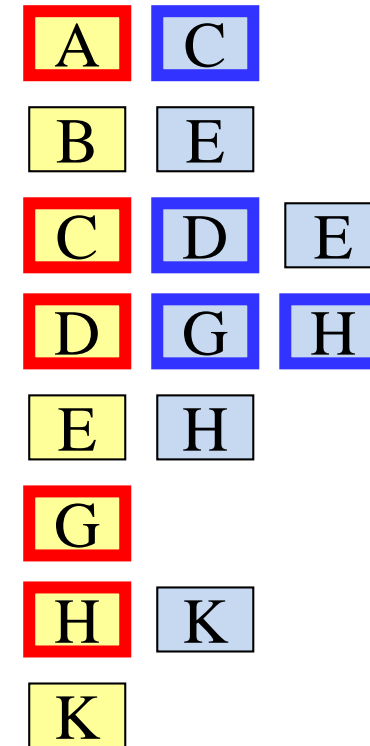
```



path: **A → C → D → H**

output: **G**

reverse:

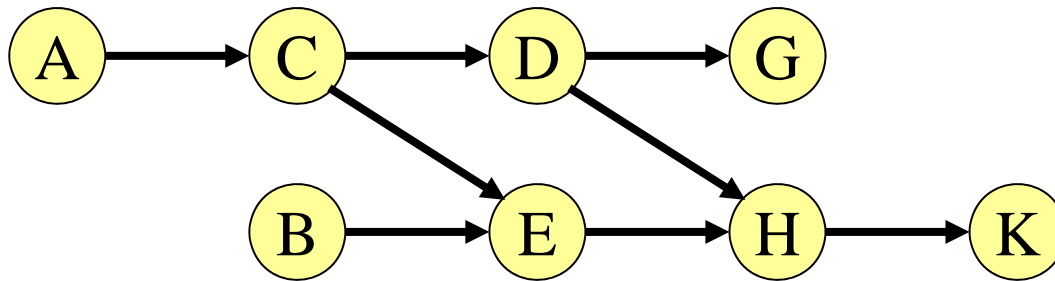


Topological Sort example

```

tsort(v) {
    mark v visited
    H → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

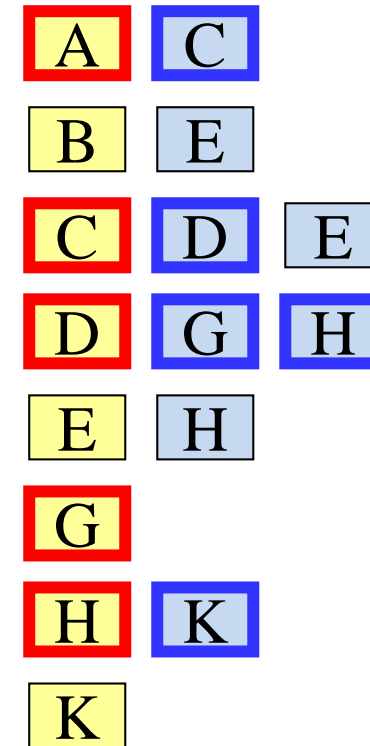
```



path: **A → C → D → H → K**

output: **G**

reverse:

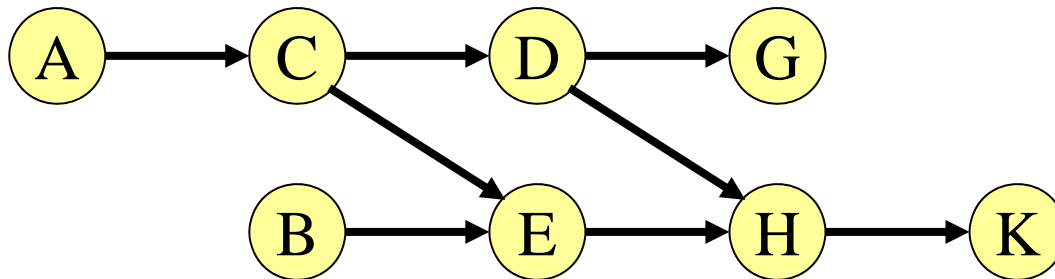


Topological Sort example

```

tsort(v) {
  K → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

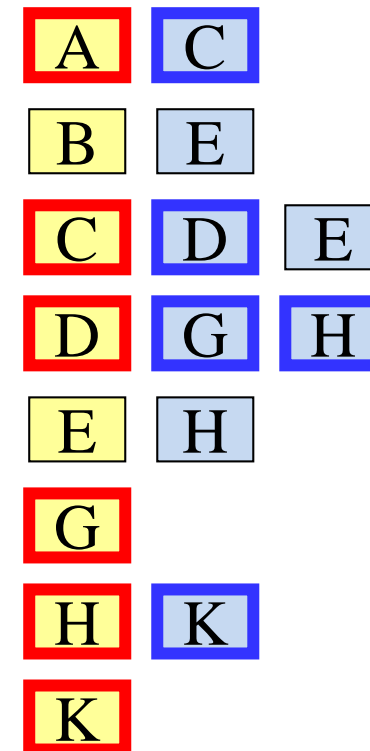
```



path: **A → C → D → H → K**

output: **G**

reverse:

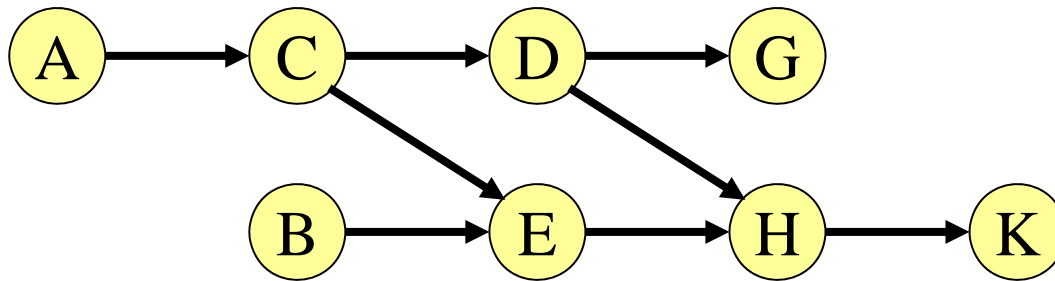


Topological Sort example

```

tsort(v) {
    mark v visited
    K → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

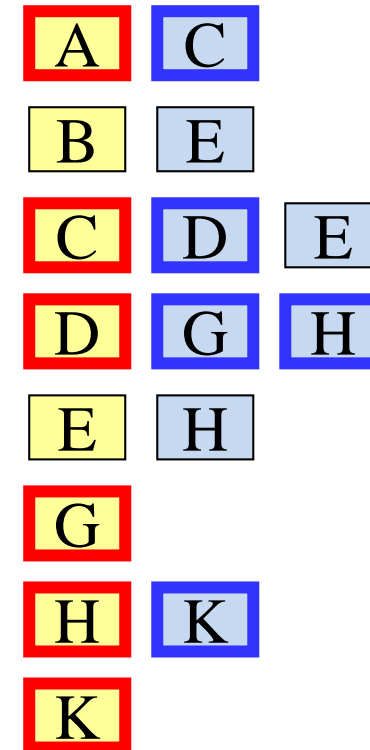
```



path: **A → C → D → H → K**

output: **G**

reverse:

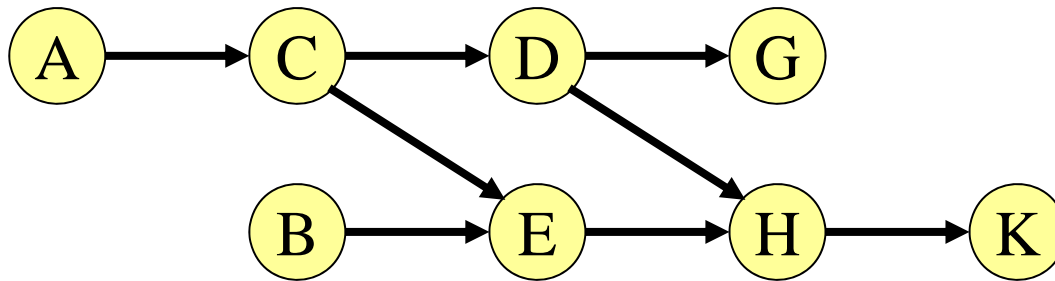


Topological Sort example

```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    K → display(v)
}

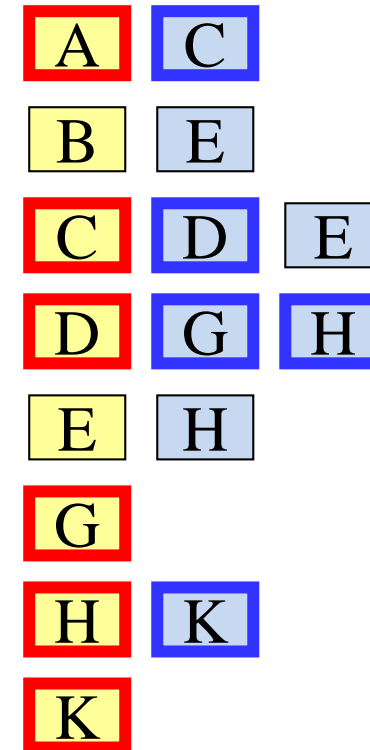
```



path: **A → C → D → H → K**

output: **G K**

reverse:

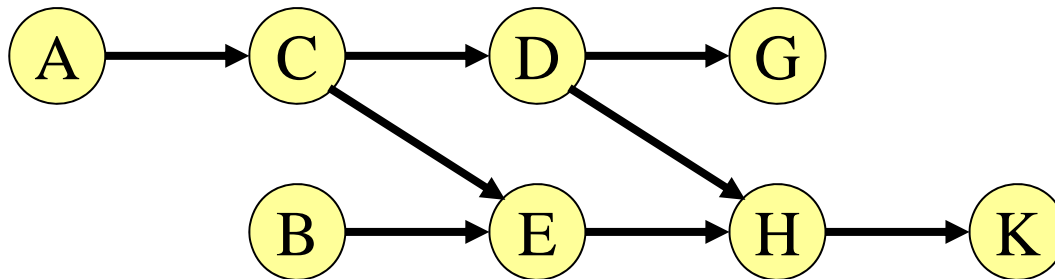


Topological Sort example

```

tsort(v) {
    mark v visited
    H → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

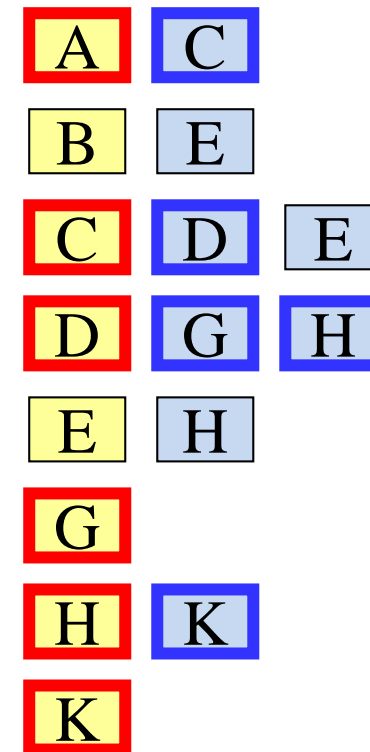
```



path: **A → C → D → H**

output: **G K**

reverse:

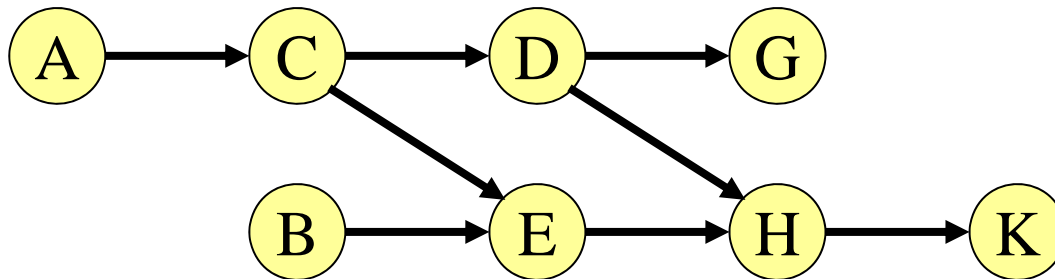


Topological Sort example

```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    H → display(v)
}

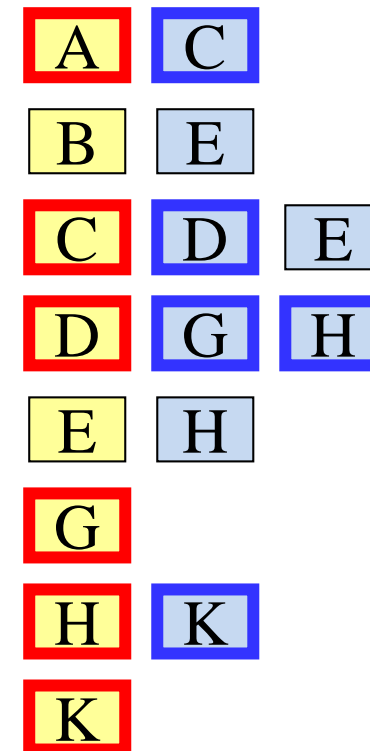
```



path: **A → C → D → H**

output: **G K H**

reverse:

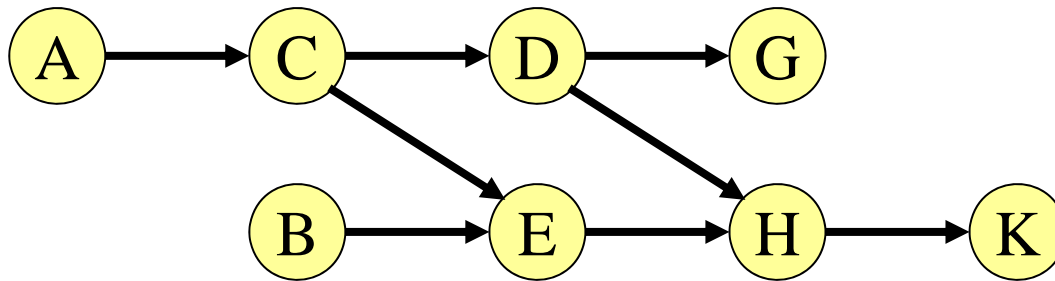


Topological Sort example

```

tsort(v) {
    mark v visited
    D → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

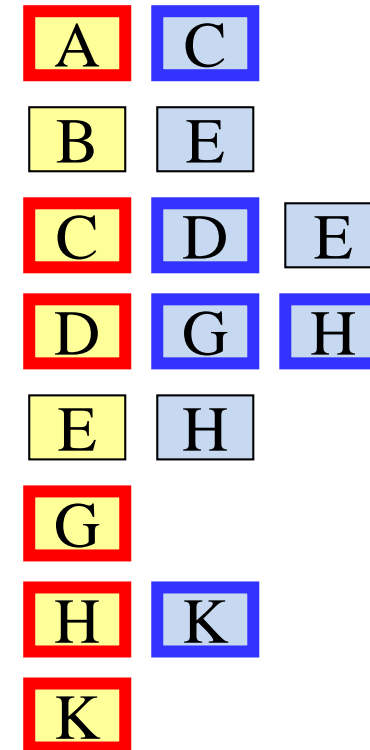
```



path: **A → C → D**

output: **G K H**

reverse:

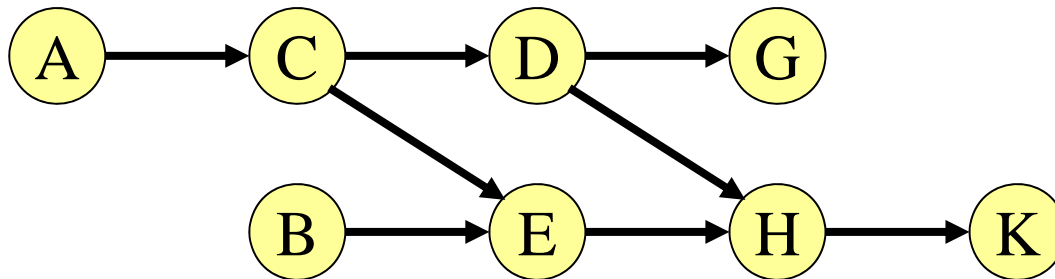


Topological Sort example

```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    D → display(v)
}

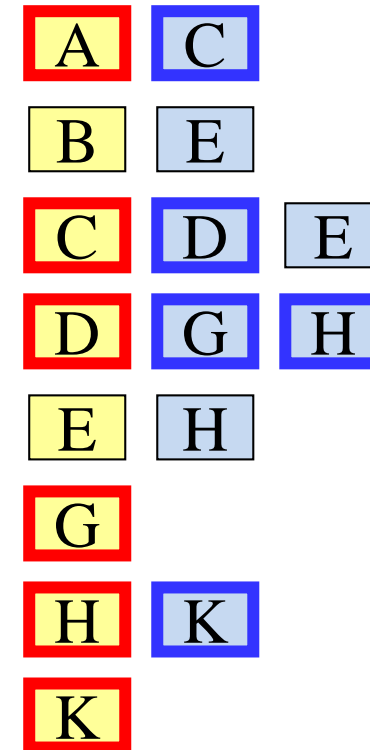
```



path: **A → C → D**

output: **G K H D**

reverse:

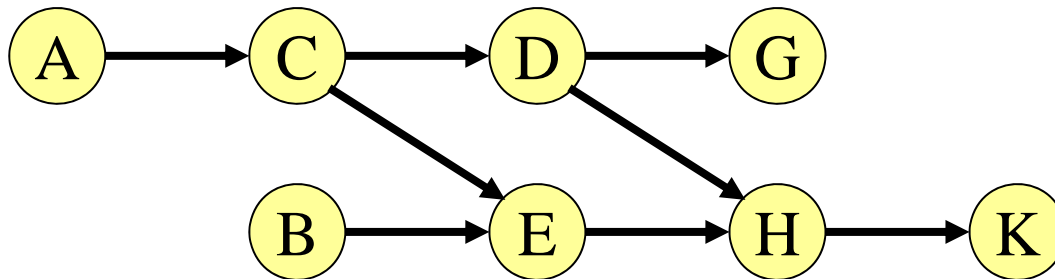


Topological Sort example

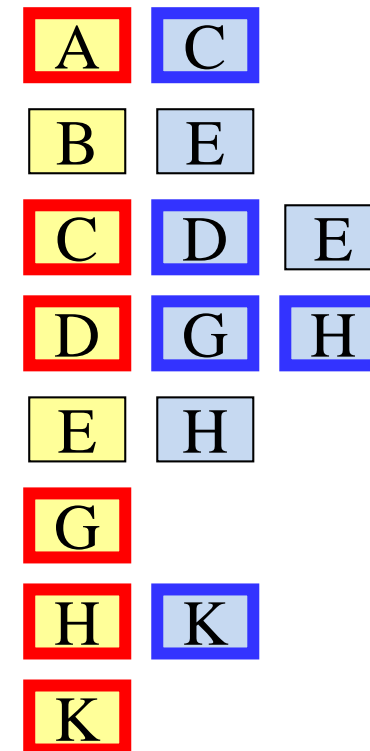
```

tsort(v) {
    mark v visited
    C→ for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

```



path: **A → C**
output: **G K H D**
reverse:

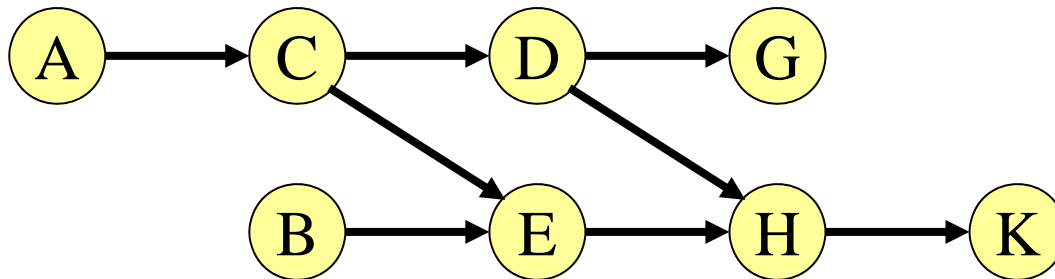


Topological Sort example

```

tsort(v) {
    mark v visited
    C→ for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

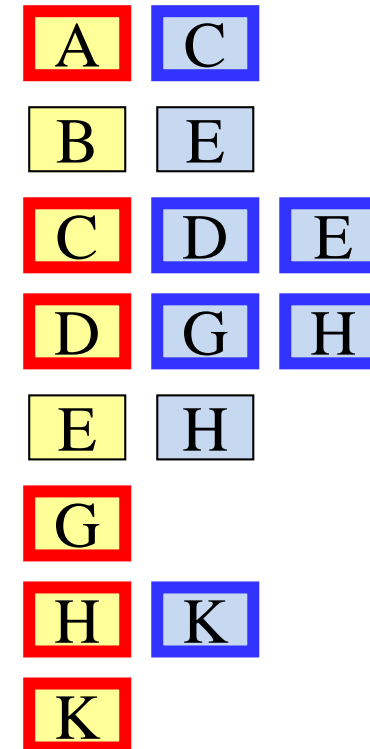
```



path: **A → C → E**

output: **G K H D**

reverse:

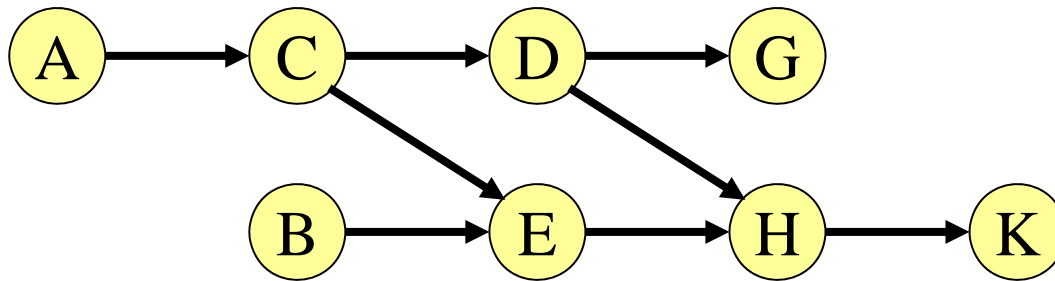


Topological Sort example

```

tsort(v) {
  E → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

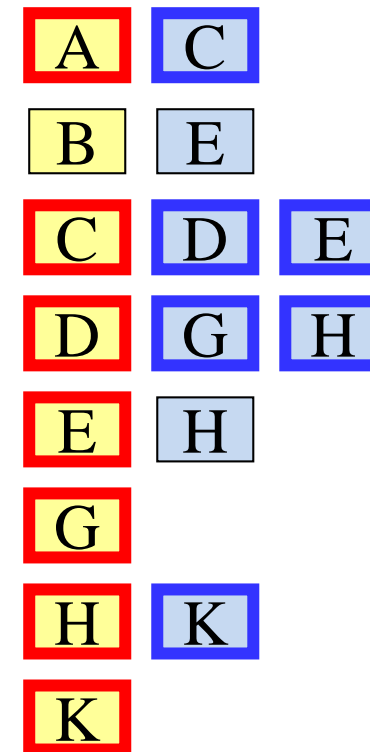
```



path: **A → C → E**

output: **G K H D**

reverse:

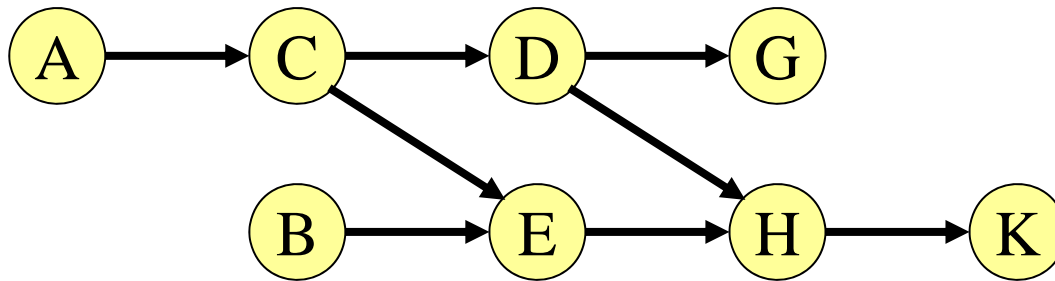


Topological Sort example

```

tsort(v) {
    mark v visited
    E → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

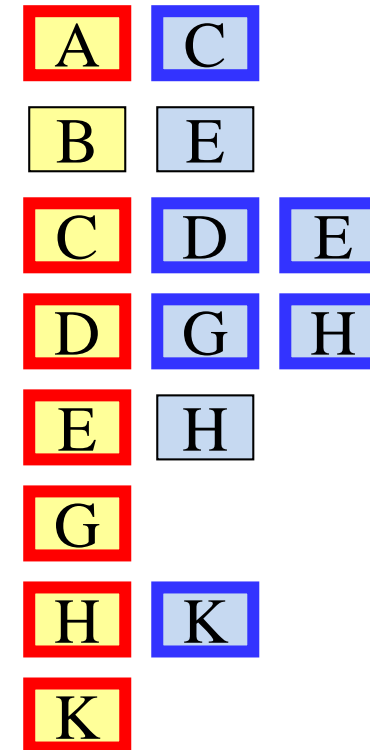
```



path: **A → C → E**

output: **G K H D**

reverse:

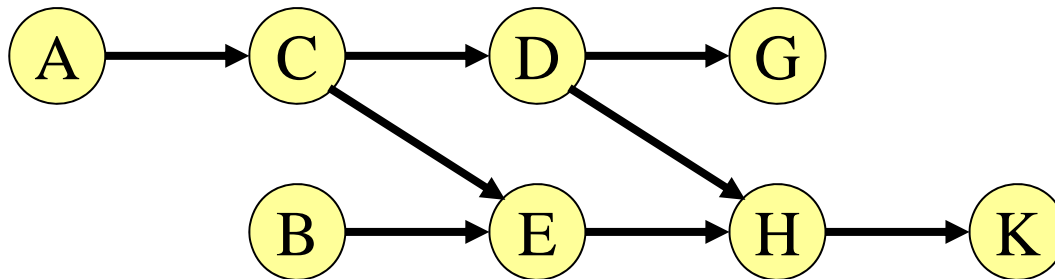


Topological Sort example

```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    E → display(v)
}

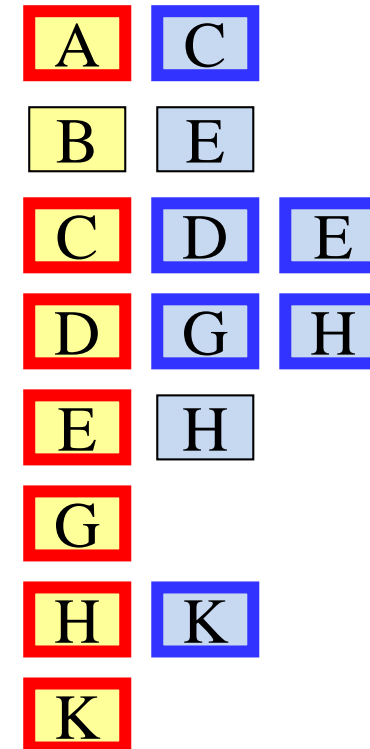
```



path: **A → C → E**

output: **G K H D E**

reverse:

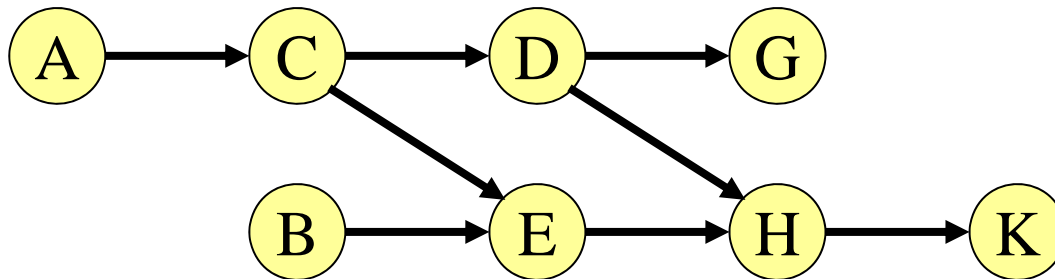


Topological Sort example

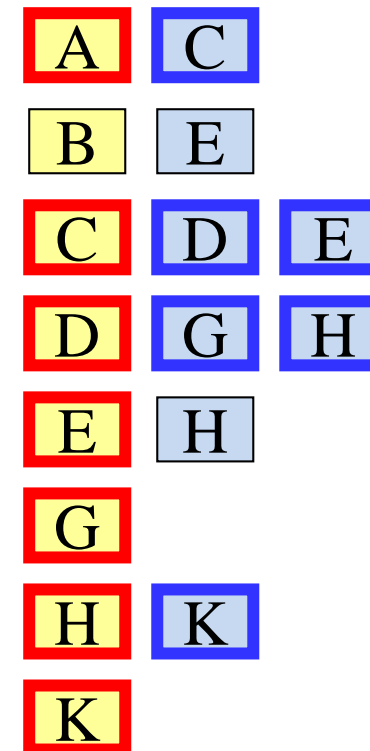
```

tsort(v) {
    mark v visited
    C → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

```



path: **A → C**
output: **G K H D E**
reverse:

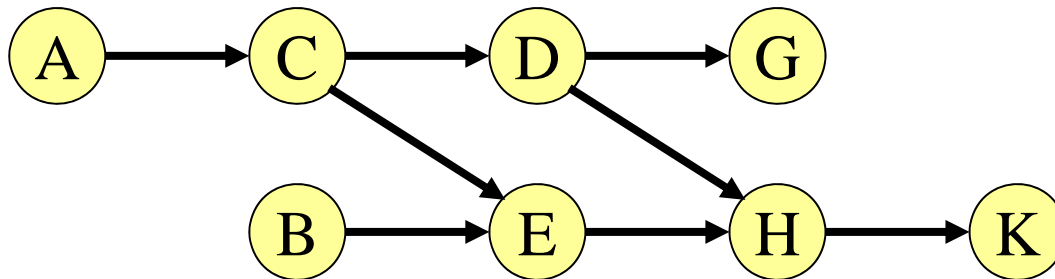


Topological Sort example

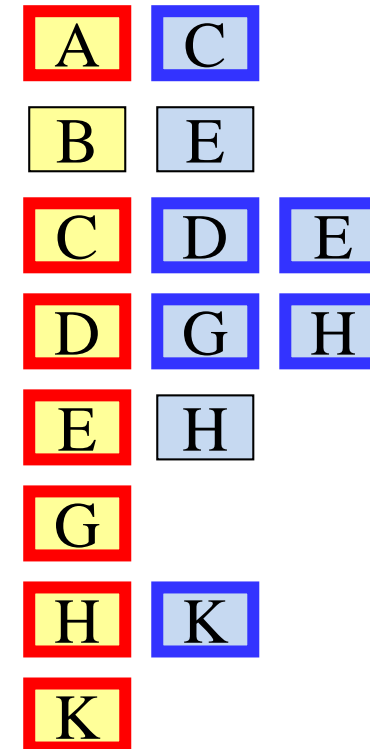
```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    C → display(v)
}

```



path: **A → C**
 output: **G K H D E C**
 reverse:

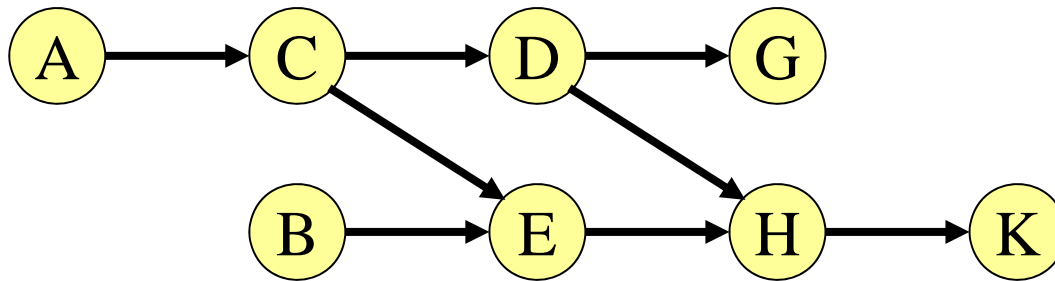


Topological Sort example

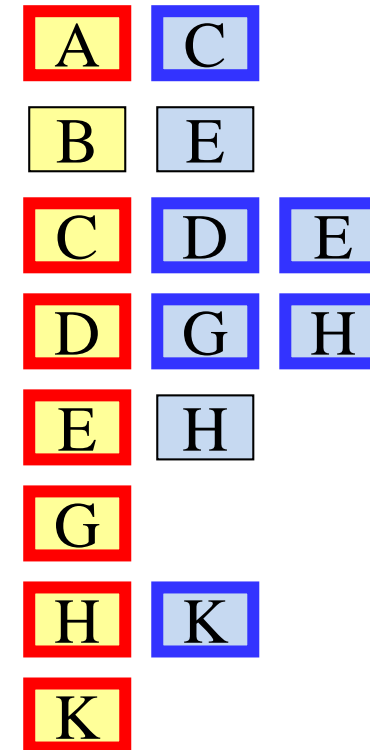
```

tsort(v) {
    mark v visited
    A → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

```



path: A
output: **G K H D E C**
reverse:

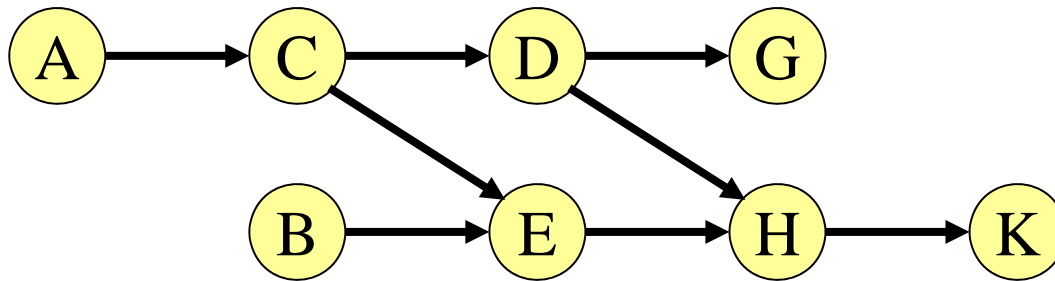


Topological Sort example

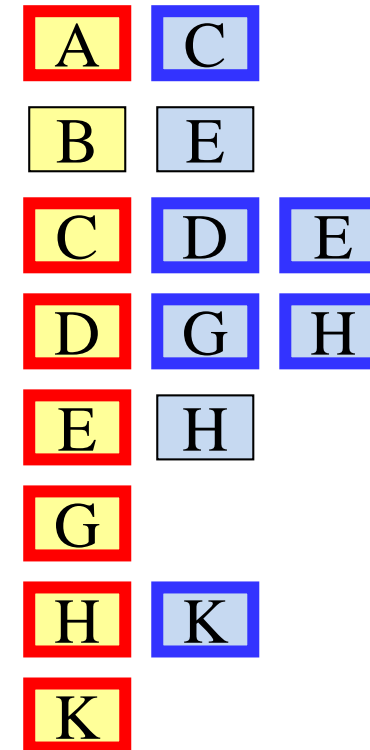
```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    A → display(v)
}

```



path: A
output: **G K H D E C A**
reverse:

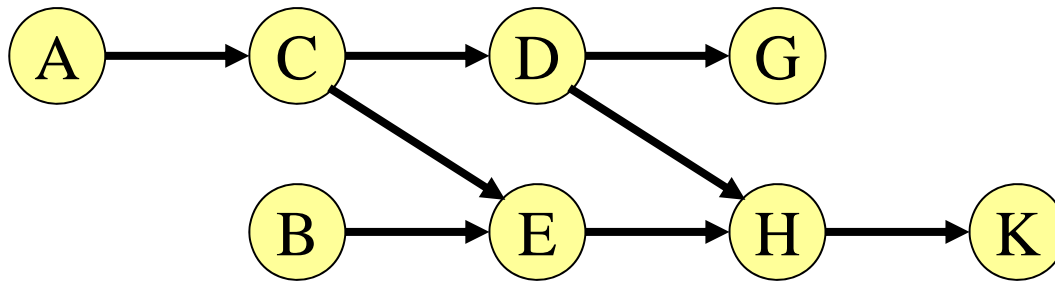


Topological Sort example

```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

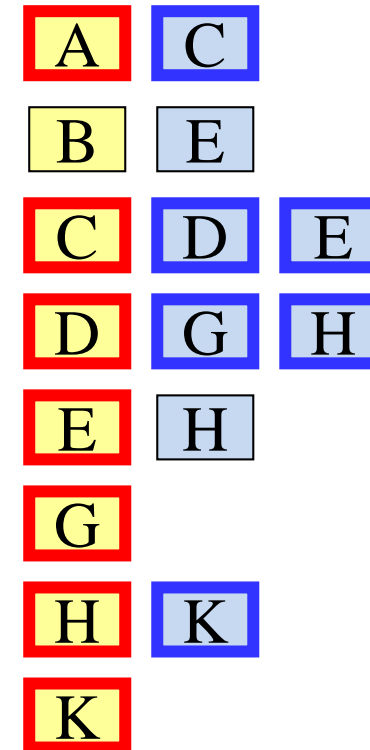
```



path:

output: **G K H D E C A**

reverse:

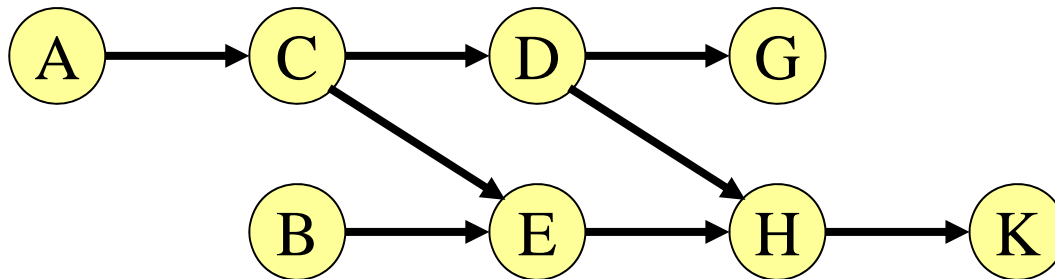


Topological Sort example

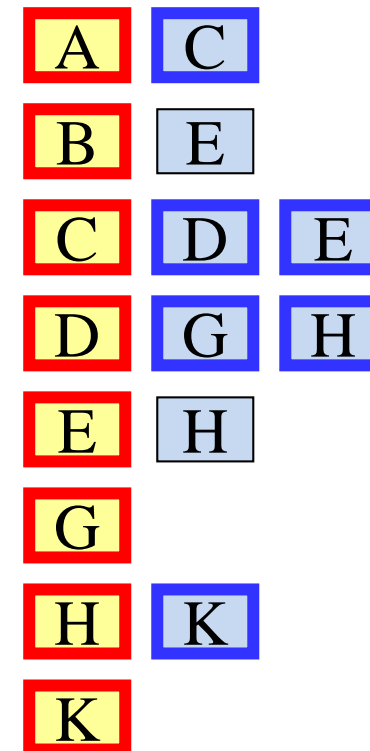
```

tsort(v) {
  B → mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

```



path: **B**
output: **G K H D E C A**
reverse:

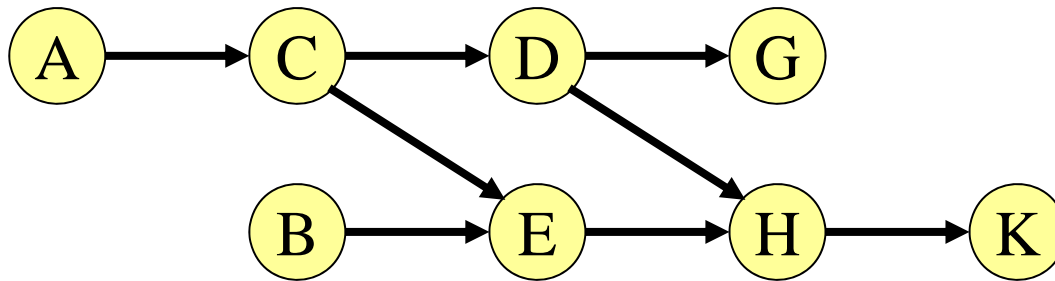


Topological Sort example

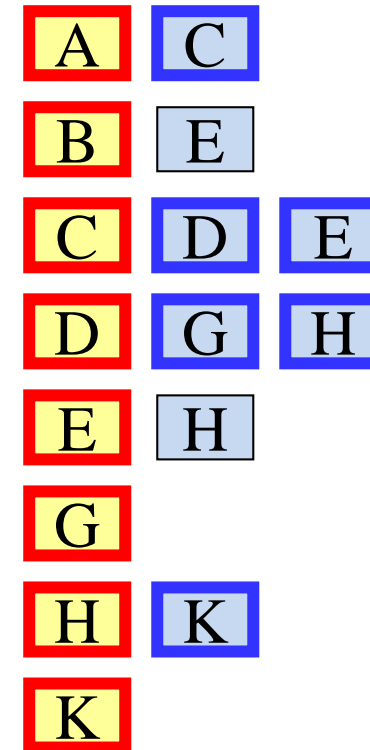
```

tsort(v) {
    mark v visited
    B → for each w adjacent to v if w unvisited tsort(w)
    display(v)
}

```



path: **B**
output: **G K H D E C A**
reverse:

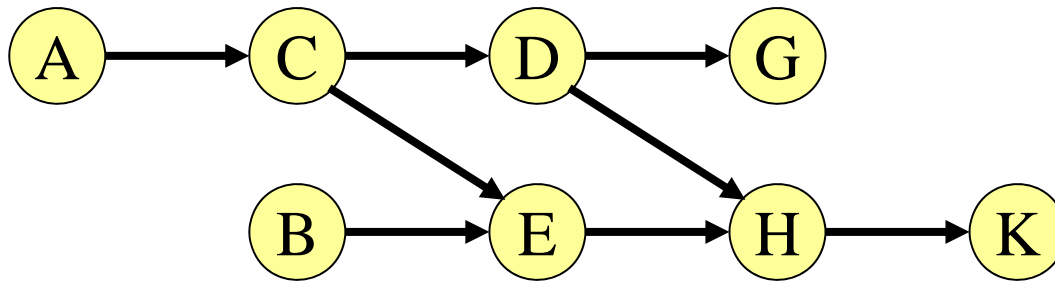


Topological Sort example

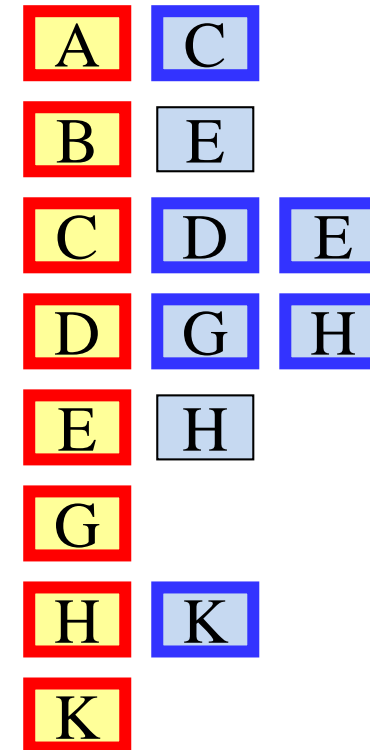
```

tsort(v) {
    mark v visited
    for each w adjacent to v if w unvisited tsort(w)
    B → display(v)
}

```



path: **B**
output: **G K H D E C A B**
reverse:

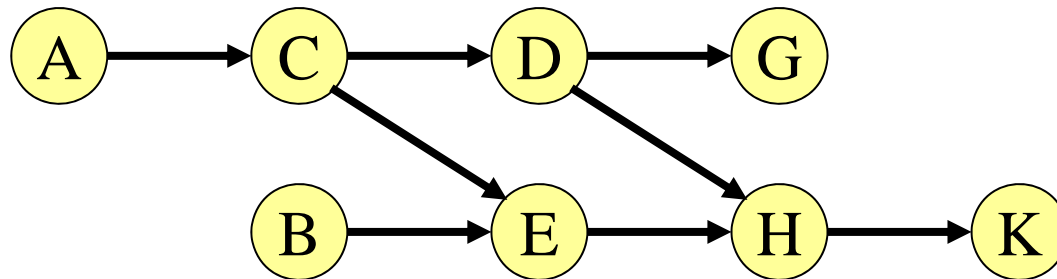


Topological Sort example

```

tsort(v) {
  mark v visited
  for each w adjacent to v if w unvisited tsort(w)
  display(v)
}

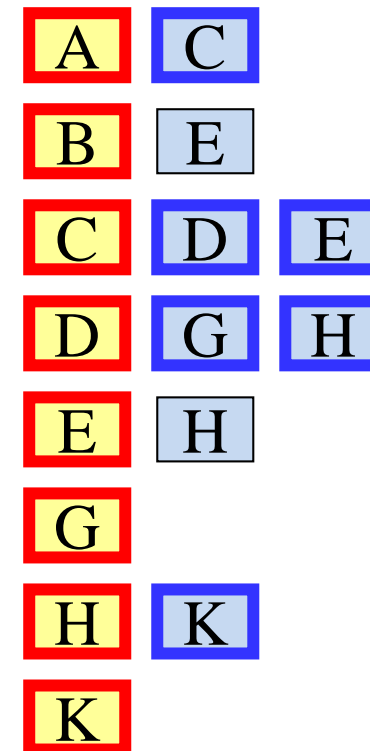
```



path:

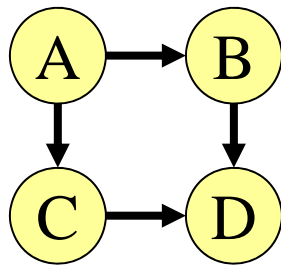
output: **G K H D E C A B**

reverse: **B A C E D H K G**

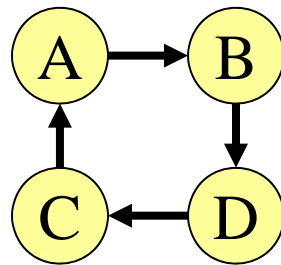


[Detecting Cycles]

- Use Warshall

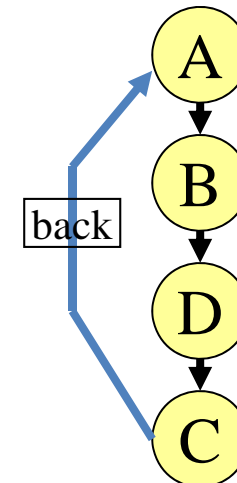
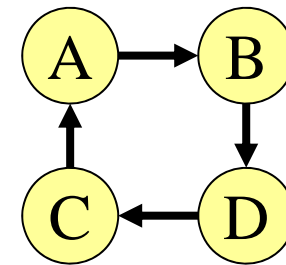
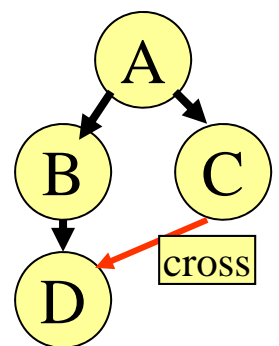
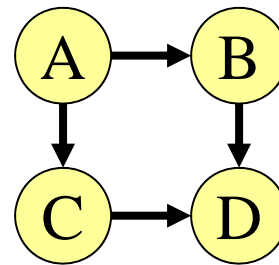


0	1	1	1
0	0	0	1
0	0	0	1
0	0	0	0



1	1	1	1
1	1	1	1
1	1	1	1
1	1	1	1

- Use depth first search

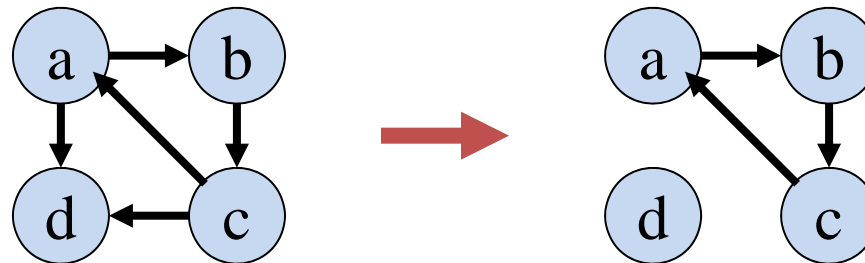


Connectivity - & Reachability (Warshall) Strongly Connected Components (SCCs)

- **Strongly connected component** of a digraph - set of vertices in which there is a **path** from any one vertex in the set to any other vertex in the set
- partition V into equivalence classes V_i , $1 \leq i \leq r$ such that v and w are equivalent iff there is a path from v to w and from w to v
- let E_i be the set of edges with head and tail in V_i
- the graphs $G_i = (V_i, E_i)$ are called **STRONGLY CONNECTED COMPONENTS (SCCs)** of G
- a **STRONGLY CONNECTED GRAPH** has only one SCC

[SCC: example]

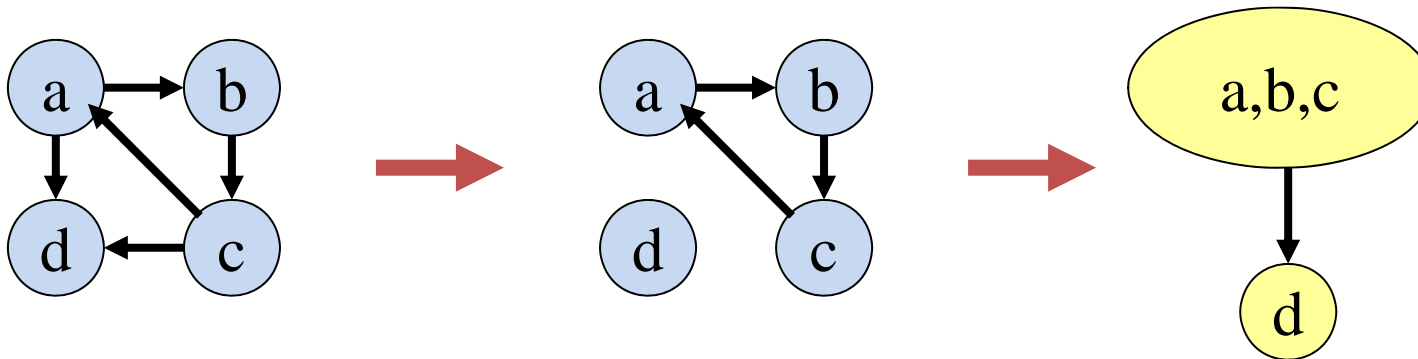
- a digraph and its strongly connected components



- every vertex of G is in some SCC
- **NOT** every edge of G is in some SCC
- **SCC = Strongly Connected Component**

[Reduced Graph]

- In a reduced graph (RG), the vertices are the **strongly connected components** of G



- edge from vertex C to C' in RG if there is an edge from some vertex in C to some vertex in C'
- RG is always a DAG since if there were a cycle, all components in the cycle would be one strong component

[SCCs: algorithm]

1. Perform a dfs and assign a number to each vertex

```
dfs(v) { mark v visited
```

```
    for each w adjacent to v if w unvisited dfs(w)
```

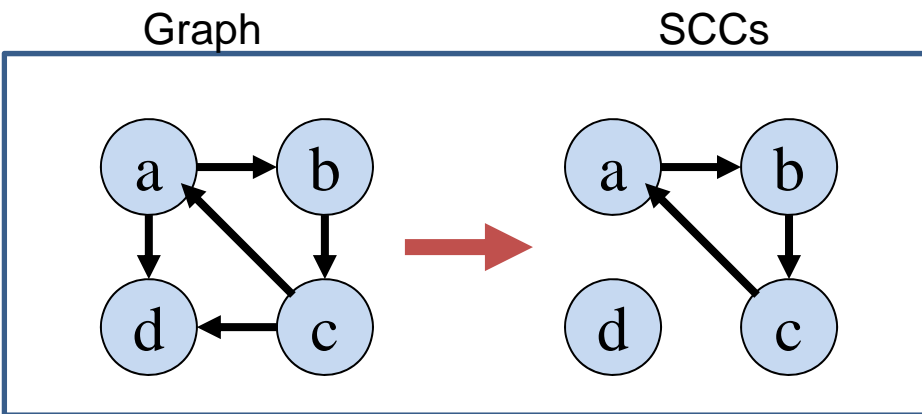
```
    number v
```

```
}
```

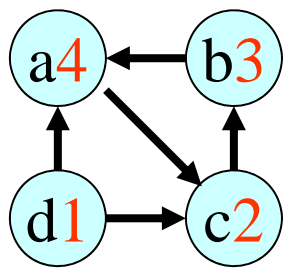
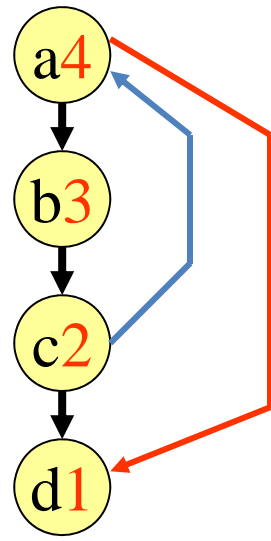
2. construct digraph G_r by reversing every edge in G
3. perform a dfs on G_r starting at highest numbered vertex
(repeat on next highest if all vertices not reached)
4. each tree in resulting spanning forest is an SCC of G

[SCCs: example]

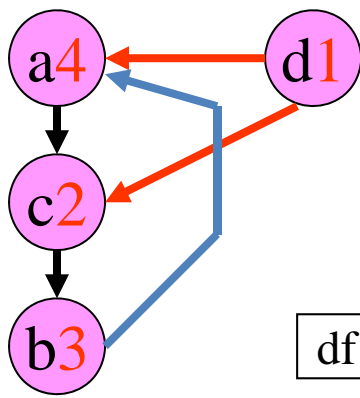
```
dfs(v) { mark v visited
for each w adjacent to v if w unvisited dfs(w)
number v
}
```



after step 1



Graph G_r



df spanning forest for G_r

[Graphs: terminology]

- $G = (V, E)$ V = set of vertices, E = set of edges (v, w)
- (v, w) ordered = **digraph** (directed graph)
- (v, w) non-ordered = **undirected graph**
- digraph: w is **adjacent** to v if there is an edge from v to w
- **DAG**: directed acyclic graph
- **path**: sequence of vertices $v_1..v_n$ where $(v_1, v_2)..(v_{n-1}, v_n)$ are edges
- **path length**: number of edges in a path
- **simple path**: all vertices are distinct (except possibly the first and last)
- **simple cycle**: simple path, length ≥ 1 , begin/end on same vertex

[Graphs: terminology]

- **Strongly Connected Component:** set of vertices in which there is a path from any vertex in the set to any other vertex in the set
- **Reduced Graph:** vertices are strongly connect components of G
- **Strongly Connected Digraph:** a path from every vertex to every other vertex
- **Complete graph:** if there is an edge between every pair of vertices
- **Implementation:** adjacency matrix or adjacency list

[Graphs: algorithms]

- **Dijkstra:** single source shortest path
- **Floyd:** all pairs shortest path
- **Warshall:** transitive closure (determines if a path exists from v to w)
- **Depth First Search:**
 - used to derive the depth first spanning forest for the graph
 - used in cycle detection
 - used to derive the strong components
- **Breadth First Search:**
 - used to derive the breadth first spanning forest for the graph
- **Topological Sort:** DAG => sequence